EAGLEHAWK NX Controller

Installation & Commissioning Instructions



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Trademark Information

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SAFETY INFORMATION

General Safety Information

- When performing any work, all instructions given by the manufacturer and in particular the safety instructions provided in these Installation and Commissioning Instructions are to be observed. Make sure that the local standards and regulations are observed at all times.
- ► The EAGLEHAWK NX System (including the EAGLEHAWK NX controller, Panel Bus I/O modules, manual disconnect modules, and auxiliary terminal packages) may be installed and mounted only by authorized and trained personnel.
- If the controller housing is damaged or missing, immediately disconnect it from any power.
- ► If the device is broken or defective, do not attempt to repair it yourself; rather, return it to the manufacturer.
- ▶ It is recommended that devices be kept at room temperature for at least 24 hours before applying power. This is to allow any condensation resulting from low shipping / storage temperatures to evaporate.
- ► The EAGLEHAWK NX System must be installed in such a manner (e.g., in a lockable cabinet) as to ensure that uncertified persons have no access to the terminals.
- ► In the case of vertical mounting on DIN rails, the EAGLEHAWK NX controller should be secured in place using a commercially-available stopper.
- ► If the EAGLEHAWK NX System is modified in any way, except by the manufacturer, all warranties concerning operation and safety are invalidated.
- ▶ Rules regarding electrostatic discharge should be followed.
- ► Use only accessory equipment which comes from or has been approved by Honeywell.

Information as per EN 60730 Purpose

The purpose of the device is: OPERATING CONTROL. The EAGLEHAWK NX controller is a multifunctional non-safety control device intended for HVAC in home (residential, commercial, and light-industrial) environments.

Construction

The EAGLEHAWK NX controller is an independently mounted electronic control unit with fixed wiring.

Mounting Method

The EAGLEHAWK NX controller is suitable for mounting as follows:

- ▶ in cabinets:
- in fuse boxes conforming with standard DIN43880, and having a slot height of max. 45 mm;
- ▶ in cabinet front doors (using accessory MVC-80-AC2);
- ▶ on walls (using accessory MVC-80-AC1).

Table 1. Information as per EN 60730

Shock protection	Class II
Pollution degree	2
Installation	Class 3
Rated impulse voltage	330 V for SELV, 2500 V for relay outputs
Automatic action	Type 1.C (micro-interruption for the relay outputs)
Software class	Class A
Ball-pressure test temperature	housing parts >75 °C terminals >125 °C

WEEE Directive

WEEE: Waste Electrical and Electronic Equipment Directive



- At the end of the product life, dispose of the packaging and product in an appropriate recycling center.
- Do not dispose of the device with the usual domestic refuse.
- Do not burn the device.

Standards, Approvals, etc.

Degree of Protection: IP20 (mounted on walls, with two accessory MVC-80-AC1 covers)
IP30 (mounted in cabinet doors, with accessory MVC-80-AC2)

Device meets EN 60730-1, EN 60730-2-9, UL60730, and UL916.

Refer to Code of Practice standards IEC 61000-5-1 and -2 for guidance.

The device complies with Ethernet Protocol versions IEEEC 802.3.

The device supports BACnet IP and BACnet MS/TP communications as per ANSI / ASHRAE 135-2012.

3RD-PARTY SOFTWARE LICENSES

This product contains software provided by third parties. See also EAGLEHAWK NX Controller – Third-Party Software Licenses (Product Literature No.: EN2Z-1041GE51).

SPECIFICATIONS OF CONTROLLER

Table 2. EAGLEHAWK NX specifications

1	rabio II I to II in this to pooli ioationo		
Power supply	19 29 VAC, 50/60 Hz or 20 30 VDC		
Power consumption	typically DC: 7 W; max. 9 W typically AC: 10 VA; max. 12 VA		
Heat dissipation	Max. 9 W at DC power supply max. 9 W at AC power supply		
Current consumption	typically DC: 300 mA; max. 375 mA typically AC: 400 mA; max. 500 mA		
Ambient temperature	0 40 °C (wall-mounting) 0 50 °C (cabinet/door mounting)		
Storage temperature	-20 +70 °C		
Humidity	5 95% r.h. non-condensing		
Dimensions	See Fig. 21 and Fig. 22.		
Degree of protection	IP20 (mounted on walls, with two accessory MVC-80-AC1 covers) IP30 (mounted in cabinet doors, with accessory MVC-80-AC2)		
Fire class	V0		
Weight	0.6 kg (excl. packaging)		

SYSTEM OVERVIEWOverview of Hardware

Table 3. Overview of models (hardware)

					order no.			
			without HMI			with HMI		
feature	description	max. cable length	CLNXEHSERIES00ND ²⁾	CLNXEHSERIES14ND ²⁾	CLNXEHSERIES26ND ²⁾	CLNXEHSERIES00D ²⁾	CLNXEHSERIES14D ²⁾	CLNXEHSERIES26D ²⁾
UI	NTC10kΩ / NTC20kΩ / 010V / slow BI, 0.4 Hz	400 m	0	4	8	0	4	8
OI .	NTC10kΩ / NTC20kΩ / 010V fix pull-up / slow BI, 0.4 Hz	400 m	0	0	2	0	0	2
ВІ	open = 24 V / closed 2.0 mA / totalizer 15 Hz	400 m	0	4	4	0	4	4
AO	011 V (max. 1 mA)	400 m	0	2	4	0	2	4
	Relay N.O. contact: 3 A, 250 VAC, 30 VDC	400 m	0	3	4	0	3	4
во	Relay N.O. contact (high in-rush): 10 A, 250 VAC, 30 VDC	400 m	0	1	1	0	1	1
	Relay N.O. contact with one common: 3 A, 250 VAC, 30 VDC	400 m	0	0	3	0	0	3
total I/Os			0	14	26	0	14	26
bus interfaces	RS485-1, isolated, BACnet MS/TP, Panel Bus, or Modbus RTU Master or Slave communication	¹⁾ 1200 m	1	1	1	1	1	1
	RS485-2, non-isolated, BACnet MS/TP, Panel Bus, or Modbus RTU Master or Slave communication (NOTE: It is imperative that the RS485-2 be powered by a power supply having the proper polarity. Failure to do so will make data transmission impossible.)	¹⁾ 1200 m	1	1	1	1	1	1
	Ethernet Interfaces (e-mail communication, browser access, BACnet IP communication, Niagara Network, Modbus TCP)	100 m	2	2	2	2	2	2
	USB 2.0 Device Interface (as Network Interface)	3 m	1	1	1	1	1	1
	USB 2.0 Host Interface (max. 200 mA)	3 m	1	1	1	1	1	1
	RS232 M-Bus communication via 15-meter-long PW3 / PW20 / PW60 converters	1)1000 m	1	1	1	1	1	1
	power LED (green)	-	1	1	1	1	1	1
	status LED (red; indicates an active alarm; is controlled by Niagara Alarm System; is configurable)		1	1	1	1	1	1
LEDs	LED L1 (yellow; lit = Daemon starting; flashing = station starting; if L2 is also flashing, then the station has started)		1	1	1	1	1	1
	LED L2 (yellow; lit = platform has started / is reachable; flashing = station has started / is reachable)	1	1	1	1	1	1	1
	bus status LEDs (for isolated RS485-1 interface)	-	2	2	2	2	2	2
					_			

¹⁾ Depending upon bit rate. However, in the case of configuration of RS485-2 for Panel Bus, the communication rate is set to 115.2 kbps, and the max. cable length is hence 800 m.

²⁾ These are unlicensed hardware versions. It will therefore be necessary for you to purchase at least one of the basic licenses (BASIC LIC) listed in Table 19.

System Architecture

An EAGLEHAWK NX System consists of the EAGLEHAWK NX controller and various Panel Bus I/O modules. The EAGLEHAWK NX controller provides interface connections, which allow connection to external systems (e.g., BACnet controllers). Via the IF-LON External Interface, the EAGLEHAWK NX can also communicate with LonWorks systems, including CentraLine LonWorks I/O Modules.

Auxiliary parts (see section "Extra Parts" on page 30) enable special features.



Fig. 1. NX - Niagara eXtended Integrated Building Management architecture

Bus and Port Connections Overview

⚠ WARNING

Risk of electric shock or equipment damage!

- ▶ Do not touch any live parts in the cabinet!
- ▶ Disconnect the power supply before making connections to or removing connections from terminals of the EAGLEHAWK NX controller or Panel Bus I/O modules.
- ▶ Do not reconnect the power supply until you have completed installation.
- ▶ Due to the risk of short-circuiting (see Fig. 24), it is strongly recommended that the EAGLEHAWK NX controller be supplied with power from a dedicated transformer. However, if the EAGLEHAWK NX controller is to be supplied by the same transformer powering other controllers or devices (e.g., the PW M-Bus Adapter), care must be taken to ensure that correct polarity is observed.
- ▶ Observe the rules regarding electrostatic discharge.

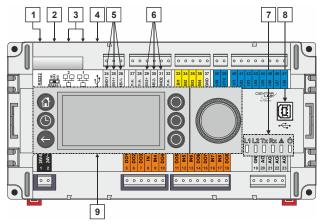


Fig. 2. Top view (with HMI and full complement of onboard I/Os)

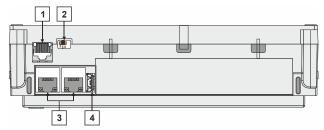


Fig. 3. Side view

Legend

- 1 RS232 / RJ45 socket (for connection of M-Bus and other RS232-based protocols; factory debugging)
- 2 Three-position slide switch (for setting bias and termination resistance of RS485-1)
- 3 Two Ethernet / RJ45 sockets (for BACnet IP communication); 10/100 Mbit/s; 1 "link" LED + 1 "activity"
- 4 USB 2.0 Host Interface (for connection of IF-LON2); max. 200 mA, high speed
- 5 RS485-1* (isolated; for BACnet MS/TP, Panel Bus, Modbus RTU communication, etc.)
- 6 RS485-2* (non-isolated; for BACnet MS/TP, Panel Bus, Modbus RTU communication, etc.)
- 7 LEDs
- 8 USB 2.0 Device Interface (for connection to COACH NX web browsers, and 3rd-party touch panels)
- 9 HMI (or RJ45 socket for connection of portable HMI)
- *Modbus RTU Master/Slave communication is possible on the two RS485 interfaces.



⚠ WARNING

Risk of electric shock or equipment damage!

▶ It is prohibited to connect any of the RJ45 sockets of the EAGLEHAWK NX controller to a so-called PoE-enabled device ("Power over Ethernet").

RS232 / RJ45 Socket

Via its RS232 / RJ45 socket, the EAGLEHAWK NX controller can be connected (using an XW586 cable) to a PW M-Bus Adapter and thus to M-Bus networks. See also section "M-Bus Connection" on pg. 50.

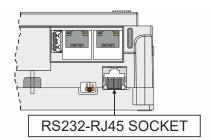


Fig. 4. RS232 / RJ45 socket

Configuring the RS232 Interface in COACH NX

When you configure the RS232 interface (for M-Bus) in COACH NX, the corresponding Port Name will appear as shown in Fig. 5.

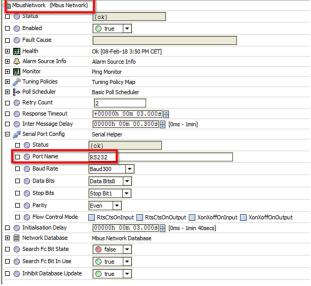


Fig. 5. Configuring the RS232 Interface in COACH NX

USB 2.0 Host Interface

Via its USB 2.0 Host interface, the EAGLEHAWK NX controller can be connected to, e.g., the IF-LON2 External Interface Adapter and thus to LonWorks networks. Max. 200 mA, high speed. See also section "LonWorks Communications" on pg. 44.

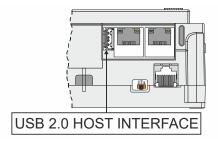


Fig. 6. USB 2.0 Host interface

USB 2.0 Device Interface

All models of the EAGLEHAWK NX controller are equipped with a USB 2.0 Device Interface at the front. This interface is for connection to COACH NX and web browsers, or 3rd-party touch panels.

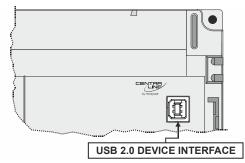


Fig. 7. USB 2.0 Device Interface

A standard USB type-B connector can be inserted into this USB 2.0 Device Interface. This USB 2.0 Device Interface is the recommended interface for connection to COACH NX.

Ethernet / RJ45 Sockets General

The EAGLEHAWK NX controller is equipped with two Ethernet / RJ45 sockets, each featuring two LEDs.

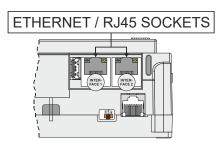


Fig. 8. Ethernet / RJ45 sockets

The two Ethernet / RJ45 sockets are 10/100-Mbit/s Ethernet interfaces permitting communication (as per IEEEC 802.3) on any supported IP network, e.g.: BACnet (IP), FOX, etc.

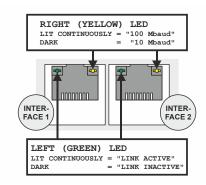


Fig. 9. Ethernet / RJ45 sockets

NOTE: The Ethernet / RJ45 sockets are usually earthgrounded. For additional information, see also "Appendix 1: Earth Grounding" on pg. 55.

The two Ethernet interfaces can be used in either of two different ways (the corresponding configuration is done in COACH NX):

- "Separated networks" (factory default).
- "Switch functionality."

See also the following two sections.

Separated Networks

The "separated networks" scenario is the factory default. In this scenario, each of the two Ethernet interfaces must be activated and located in a different subnet.

Switch Functionality

In this scenario, one of the two Ethernet interfaces is deactivated (using COACH NX – see section "Disabling an Ethernet Interface" below). The deactivated Ethernet interface will now function in the loop-through (daisy-chain) mode and can therefore be used to continue the data line.

The following limitations apply:

1. Only daisy-chain configurations are allowed.

- A maximum of five Ethernet-capable devices (including EAGLEHAWK NX controllers) are allowed (failure to observe this limitation will result in signal delays and will degrade data transmission).
- 3. The maximum distance between any two of the Ethernetcapable devices in the daisy chain is 100 meters.
- 4. Connect the devices using CAT5 cable or better.

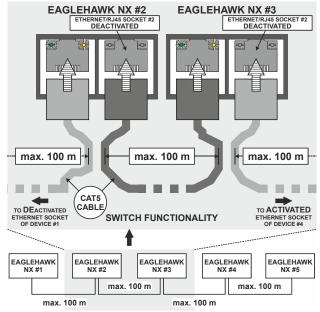


Fig. 10. Allowed Ethernet wiring topology ("switch functionality")

NOTE: During any power failure of the EAGLEHAWK NX, the switching functionality is inoperative.

Disabling an Ethernet Interface

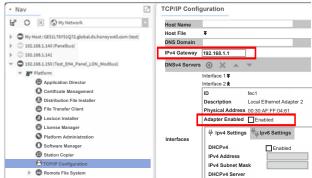


Fig. 11. Entering gateway address, disabling one of the two Ethernet interfaces in COACH NX

To ensure that the discovery of devices, datapoints, schedules, and histories does not fail, during configuration in COACH NX, you should enter a gateway address. If there is no gateway address physically given by the Network Setting, then enter a gateway address that relates to the IP address of the enabled Ethernet Interface. In Fig. 11, the gateway address is 192.168.1.1, hence the IP address of Ethernet adapter 1 must be in the range of 192.168.1.2 to 192.168.1.255.

Default IP Addresses of Ethernet Interfaces 1 and 2

In any case, the default IP address of Ethernet interface 1 is: 192.168.200.20, mask 255.255.255.0

and the default IP address of Ethernet interface 2 is: 192.168.201.20, mask 255.255.255.0

LEDs

The EAGLEHAWK NX controller features the following LEDs:



Fig. 12. EAGLEHAWK NX controller LEDs Table 4. EAGLEHAWK NX controller LEDs

symbol	color	function, description			
L1	yellow	Lit = Daemon starting; flashing = station starting; if L2 is also flashing, then the station has started.			
Lit = platform has started / is reachable; yellow flashing = station has started / is reachable.		flashing = station has started / is			
Тх	yellow	RS485-1 status LED indicating transmission of communication signals.			
Rx	yellow	RS485-1 status LED indicating reception of communication signals.			
\triangle	red	Indicates an active alarm; is controlled by Niagara Alarm System; is configurable.			
()	green	Power LED.			

See also section "EAGLEHAWK NX Controller Troubleshooting" on page 53 for a detailed description of the behaviors of the LEDs and their meanings.

RS485 Interfaces

General

The EAGLEHAWK NX controller features two RS485 interfaces:

- RS485-1 (consisting of push-in terminals 24 [GND-1], 25, and 26) is isolated and can be used for any RS485-based communication protocol available within Niagara Ecosystems, e.g.: Panel Bus, BACnet MS/TP, etc.
- RS485-2 (consisting of push-in terminals 29, 30, and 31 [GND-2]) is non-isolated (i.e. GND-2 is internally connected with terminal 1 [24V-0]) and can be used for any RS485-based communication protocol available within Niagara Ecosystems, e.g.: Panel Bus, BACnet MS/TP, etc.

NOTE: It is imperative that the RS485-2 be powered by a power supply having the proper polarity. Failure to do so will make data transmission impossible.

Configuring the RS485 Interfaces in COACH NX

When you configure the two RS485 interfaces (for Modbus, BACnet MS/TP, or Panel Bus) in COACH NX, the corresponding Port Names will appear as shown in Fig. 13.

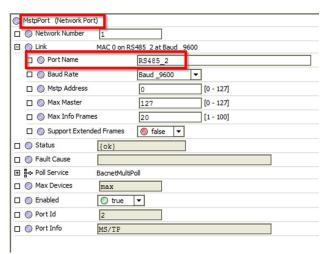


Fig. 13. Configuring the RS485 interfaces in COACH NX

RS485-1 Bias and Termination Resistors

RS485-1 is equipped with a three-position slide switch which can be used to switch its bias resistors OFF (position "MID" – this is the default), ON (position "BIAS"), and ON with an additional 150Ω termination resistor (position "END").

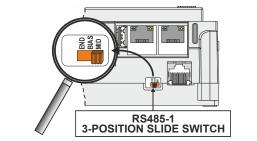


Fig. 14. RS485-1 three-position slide switch

The recommended slide switch setting depends upon the location and usage of the given EAGLEHAWK NX – see Fig. 15 through Fig. 17 and Table 5; it also depends upon the selected communication protocol (BACnet MS/TP, Panel Bus, or Modbus RTU Master communication, respectively).

Table 5. Recommended slide switch settings

setting	remarks
END	Controllers located on either end of bus should have this setting.
BIAS	In small bus networks, a min. of one and a max. of two controllers should have this setting.
MID	All other controllers (not set to "END" or "BIAS") on bus should have this setting (which is the default).

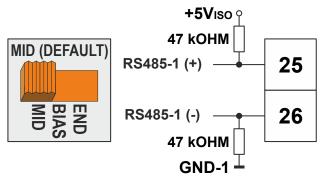


Fig. 15. RS485-1 three-position slide switch setting MID

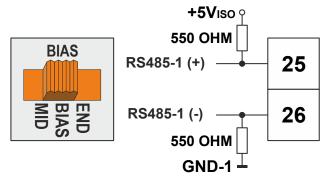


Fig. 16. RS485-1 three-position slide switch setting BIAS

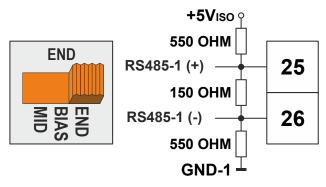


Fig. 17. RS485-1 three-position slide switch setting END

NOTE: All terminals are protected (up to 24 VAC) against short-circuiting and incorrect wiring – except when the 3-position slide switch is set to "END," in which case the terminals of the RS485-1 bus (24, 25, and 26) have no such protection. Higher voltages may damage the device.

NOTE: According to BACnet standards, a minimum of one and a maximum of two BACnet devices must have its/their bias resistors switched ON. In the case of the RS485-1 interface of the EAGLEHAWK NX, setting its slide switch to either "BIAS" or "END" fulfills this requirement.

RS485-2 Bias and Termination Resistors

The RS485-2 interface is not affected by the aforementioned three-position slide switch. The 550Ω bias resistors and 130Ω termination resistor of the RS485-2 are thus always ON.

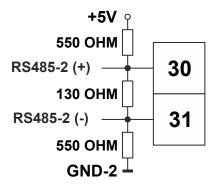


Fig. 18. RS485-2 bias and termination resistors

NOTE: GND-2 is internally connected with 24V-0 (terminal 1)

RS485 Standard

According to the RS485 standard (TIA/EIA-485: "Electrical Characteristics of Generators and Receivers for Use in Balanced Digital Multipoint Systems"), only one driver communicating via an RS485 interface may transmit data at a time. Further, according to U.L. requirements, each RS485 interface may be loaded with a max. of 32 unit loads. E.g., CentraLine devices have as little as ¼ unit load each, so that up to 128 devices can be connected.

BACnet MS/TP connections to the RS485 interfaces must comply with the aforementioned RS485 standard. Thus, it is recommended that each end of every connection be equipped with one termination resistor having a resistance equal to the cable impedance (120 Ω / 0.25 – 0.5 W). RS485 systems frequently lack a separate signal ground wire.

However, the laws of physics still require that a solid ground connection be provided for in order to ensure error-free communication between drivers and receivers – unless all of the devices are electrically isolated and no earth grounding exists.

IMPORTANT

In the case of new EAGLEHAWK NX controller installations, we strongly recommend using a separate signal ground wire. Doing otherwise may possibly lead to unpredictable behavior if other electrically non-isolated devices are connected and the potential difference is too high.

In the case of the installation of EAGLEHAWK NX controllers in already-existent RS485 two-wire systems (e.g., when replacing PANTHER and LION controllers with EAGLEHAWK NX controllers), not using a separate signal ground wire will probably have no undesirable effects.

The cable length affects the communication rate. Table 6 provides a few examples.

Table 6. Bit rate vs. max. cable length for RS485

Bit rate	Max. cable length (L)
9.6 - 76.8 kbps	1200 m
*115.2 kbps	800 m

* In the case of configuration of RS485-2 for Panel Bus, the communication rate is set to 115.2 kbps.

For information on wire gauge, max. permissible cable length, possible shielding and grounding requirements, and the max. number of devices which can be connected to a bus, refer to standard EIA-485.

Modbus Connection

The EAGLEHAWK NX controller can function as a Modbus Master or Slave. In general, the RS485 wiring rules must be followed.

Wiring Topology

Only daisy-chain wiring topology is allowed.

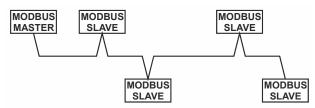


Fig. 19. Allowed Modbus wiring topology

Other wiring topologies (e.g., star wiring, or mixed star wiring and daisy chain wiring) are prohibited; this is to avoid communication problems of the physical layer.

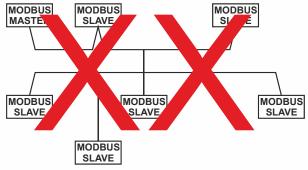


Fig. 20. Prohibited Modbus wiring topology (example)

Cables

See also section "EIA 485 Cable Specifications" on pg. 40. Use shielded twisted pair cable J-Y-(St)-Y 4 x 2 x 0.8.

You must use three wires:

- · One wire for Modbus +
- · One wire for Modbus -
- · One wire for the signal common

When using one pair for Modbus (+) and Modbus (-) and one wire of another pair for the signal common, CAT5 cable may also be used.

For connection details, see section "Modbus Connection" on pg. 48.

Shielding

Shielding is especially recommended when the Modbus cable is installed in areas with expected or actual electromagnetic noise. Avoiding such areas is to be preferred.

Use shielded twisted pair cable shielded twisted pair cable J-Y-(St)-Y $4 \times 2 \times 0.8$ and connect the Modbus to a noise-free earth ground – only once per Modbus connection.

RS485 Repeaters

RS485 repeaters are possible, but have not been tested by Honeywell. Hence it is within responsibility of the installing / commissioning person to ensure proper function.

NOTE: Each Modbus segment will require its own line polarization and line termination.

Modbus Master Specifications

Modbus Compliance

As per the Modbus standard, the EAGLEHAWK NX controller is a conditionally compliant "regular" Modbus device.

The EAGLEHAWK NX controller differs from an unconditionally compliant "regular" Modbus device in that it does not support communication rates of 1.2, 2.4, and 4.8 kbps (because these communication rates are not market-relevant).

Physical Layer

2-wire serial line RS485 (EIA-485) (with additional common) Communication rates: 9.6, 19.2, 38.4, 57.6, 76.8, and

115.2 kbps supported.

Max. number of devices: 32

Cable and wiring specifications: See section "Wiring and Set-Up" on pg. 20.

Communication Mode

Typically: Modbus Master.

Transmission Mode

RTU (Remote Terminal Unit) and (via Ethernet) TCP/IP.

Address Range

Modbus slaves can have an address between 1 and 247. Discrete Inputs, Coils, Input Registers and Holding Registers can have an address between 1 and 65534.

Further Information

For further information, please refer to the Modbus Driver documentation (docModbus.pdf).

SET UP AND CONFIGURATION

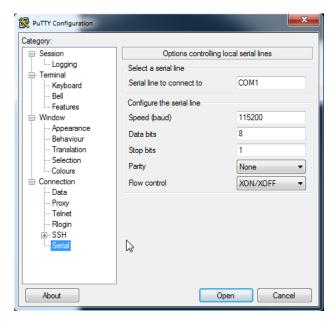
General

You can access the EAGLEHAWK NX controller via the RS232 interface using a terminal program (serial port) such as "PuTTY." This can be helpful in the following cases:

- When the EAGLEHAWK NX controller cannot be accessed via network. Solution: The network can be configured to the required settings (see step 6 below).
- When the EAGLEHAWK NX controller application or status is unknown Solution: The controller can be reset to the factory defaults (see step 7 below).

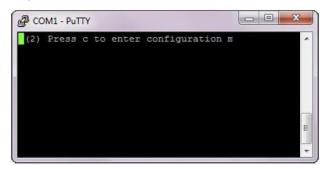
Before proceeding (see section "Procedure" below), you must first connect the RS232 interface of the EAGLEHAWK NX controller and the PC on which PuTTY is running using the following two cables connected end-to-end: XW586 and XW585.

The interface parameters for serial communication are as shown in the following screenshot:



Procedure

 Start PuTTY. As soon as the following line displays, press c



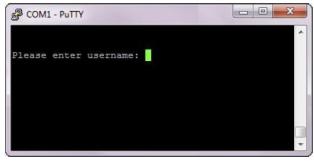
RESULT: The Boot menu displays.

```
Boot menu

1 - Login
F - Reset to factory default
R - Reboot
x - Exit
Enter your choice (51s):
```

2. To login and change the IP address and/ or configure further network settings, press 1.

RESULT: You will be asked to enter your username.



3. Enter the user name and press Enter.

RESULT: You will be asked to enter your password.

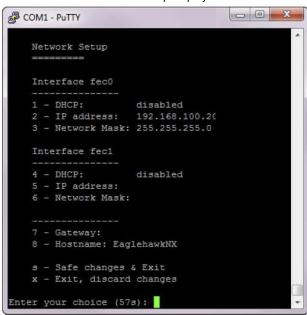


4. Enter the password and press Enter.

RESULT: The Main menu displays.

5. Press 1 in the Main menu.

RESULT: The Network Setup displays.

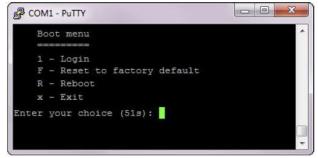


- Configure the network as desired by applying the available options displayed.
- 7. To reset the controller to factory defaults, press F in the Boot menu.

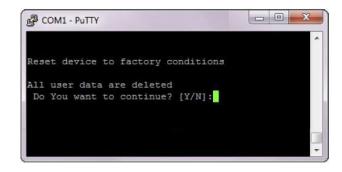
ATTENTION: Resetting the controller to its factory defaults will result in the following:

- · The station will be deleted.
- The platform credentials will be deleted.
- The IP settings will be reset to the factory defaults (see section "Default IP Addresses of Ethernet Interfaces 1 and 2" on pg. 9).

RECOMMENDATION: Before leaving (closing) the terminal program, go to "Network Setup" and enter the desired IP settings.



8. Reset the controller by entering Y.



FINISHED!

Configuring Ports to Enable Webserver Functions

The EAGLEHAWK NX controller provides webserver functionality, e.g., for using the CentraLine N4 Supervisor. In order to use webserver functions, the http and https standard port settings must be changed as follows:

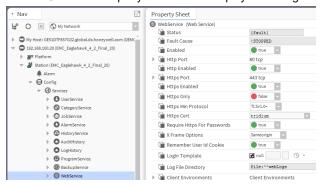
- http standard port 80 to 8080
- https standard port 443 to 8443

After the changes are done, the controller is reachable via both pairs of ports, i.e., via the old standard ports and via the newly set ports.

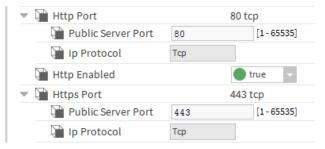
Procedure

 In the COACH NX Nav tree, expand the Services folder, and then double-click WebService.

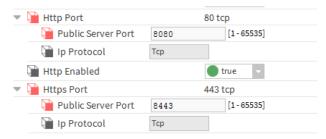
RESULT: The Property Sheet Sheet displays to the right.



2. Expand the Http Port and Https Port options.

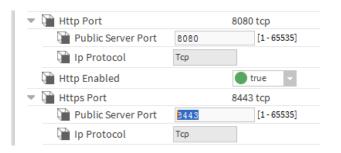


3. Change Http Port to 8080 and the Https Port to 8443.



4. Click the Save button at the bottom.

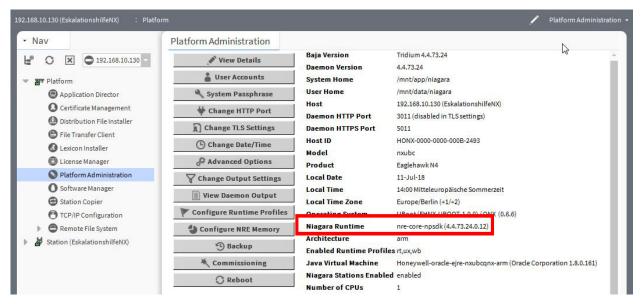
RESULT: The changed port settings are saved.



FINISHED!

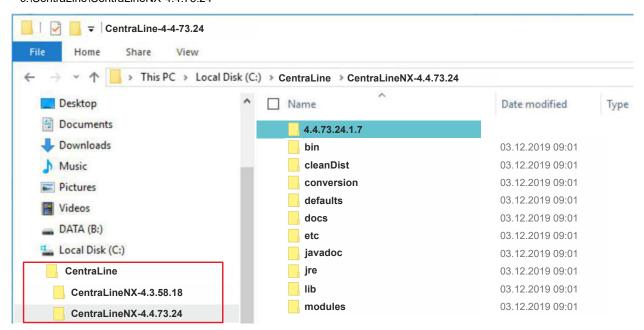
Firmware Update

Check the firmware version installed in your EAGLEHAWK NX as follows:
 Open COACH NX, go to the Platform/Platform Administration, and check the version of the Niagara Runtime installed in the EAGLEHAWK NX.



- 2. Close COACH NX.
- 3. Get the firmware upgrade package from the CentraLine Partnerweb. At present, this package is contained in EAGLEHAWKNX-SupportPackage_17July2018.zip.

4. Navigate with Windows Explorer to your installation folder. For version NX 4.4.73.24, the default folder is c:\CentraLine\CentraLine\X-4.4.73.24

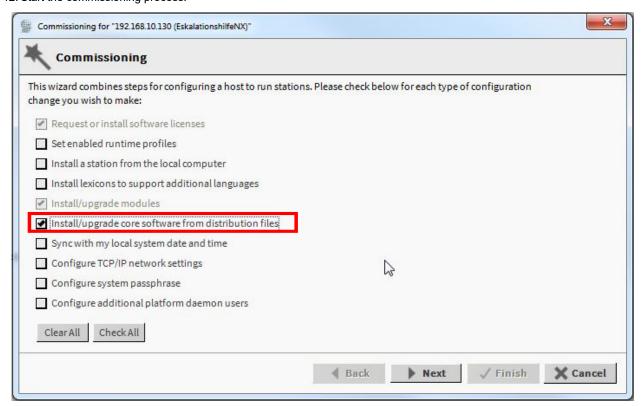


- 5. Double click the "Workbench User Home" link, you will be redirected to the user home
- 6. Navigate to <user home>/sw/inbox folder. Resulting path for 4.4. is: C:\Users\<your username>\Niagara4.4\tridium\sw\inbox
- 7. Copy and paste all four firmware files (contained in the firmware upgrade package) into the aforementioned inbox.
- 8. Run the platform daemon.
- 9. Restart COACH NX.

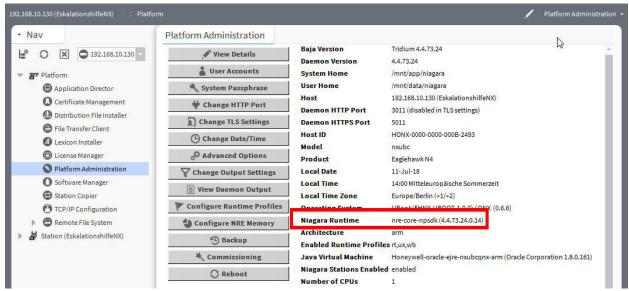
10. Connect to the EAGLEHAWK NX and start the Commissioning Wizard.



- 11. Deactivate all checkboxes; only Update Core Software needs to be selected.
- 12. Start the commissioning process.



13. After a successful update, the Platform Administration should show the new firmware version in the Niagara Runtime field:



FINISHED!

MOUNTING/DISMOUNTING

Before Installation

IMPORTANT

To allow the evaporation of any condensation resulting from low shipping / storage temperatures, keep the controller at room temperature for at least 24 h before applying power.

US requirement, only: This device must be installed in a UL-listed enclosure offering adequate space to maintain the segregation of line voltage field wiring and Class 2 field wiring.

In the case of vertical mounting on DIN rails, the EAGLEHAWK NX controller should be secured in place using a commercially-available stopper. See also the EAGLEHAWK NX - Mounting Instructions (MU1Z-1039GE51).

Dimensions

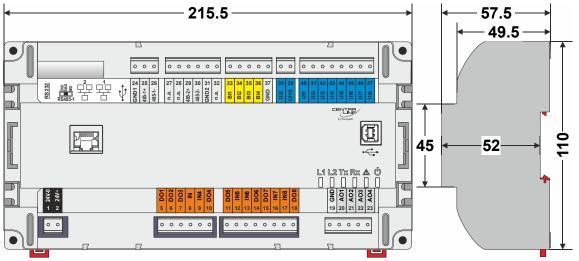


Fig. 21. EAGLEHAWK NX controller (w/o HMI but with RJ45 socket for connection of portable HMI, and with full complement of onboard I/Os), dimensions (in mm)

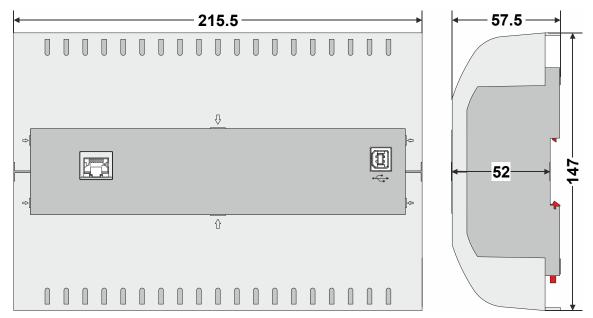


Fig. 22. EAGLEHAWK NX controller with covers, dimensions (in mm)

NOTE: Use of the covers (MVC-80-AC1) obstructs access to the Ethernet and USB 2.0 Host Interfaces and RS232 socket.

WIRING AND SET-UP

General Safety Considerations

- All wiring must comply with applicable electrical codes and ordinances, including VDE, National Electric Code (NEC) or equivalent, and any local regulations must be observed. Refer to job or manufacturer's drawings for details. Local wiring guidelines (e.g., IEC 364-6-61 or VDE 0100) may take precedence over recommendations provided here.
- Electrical work should be carried out by a qualified electrician.
- Electrical connections must be made at terminal blocks.
- For Europe, only: To comply with CE requirements, devices with a voltage in the range of 50 ... 1000 VAC or 75 ... 1500 VDC which are not provided with a supply cord and plug or with other means for disconnection from the supply having a contact separation of at least 3 mm in all poles must have the means for disconnection incorporated in the fixed wiring.

⚠ WARNING

Risk of electric shock or equipment damage!

- Observe precautions for handling electrostatic sensitive devices
- ▶ Do not touch any live parts in the cabinet.
- ▶ Do not open the controller housing.
- Disconnect the power supply before making connections to or removing connections from terminals of the EAGLEHAWK NX controller and devices wired to it.
- ▶ Do not use spare terminals as wiring support points.
- ➤ To prevent risk of injury due to electrical shock and/or damage to the device due to short-circuiting, low-voltage and high-voltage lines must be kept separate from one another.
- ▶ All terminals are protected (up to 24 VAC) against short-circuiting and incorrect wiring (unless the 3-position slide switch is set to "END," in which case the terminals of the RS485-1 bus [24, 25, and 26] have no such protection). Higher voltages may damage the device.
- Do not reconnect the power supply until you have completed the installation.

Fusing Specifications

System Fusing

We recommend that the system be equipped with an external fuse.

Fusing of Active Field Devices

F2 (depends upon given load).

Lightning Protection

Please contact your local Honeywell representative for information on lightning protection.

Wiring Terminals

The EAGLEHAWK NX is equipped with push-in terminal plugs.

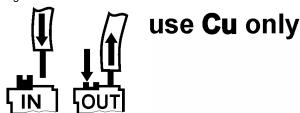


Fig. 23. Inserting/removing wires from push-in terminals

NOTE: With solid conductors, ferrules are prohibited.
 NOTE: Use only one conductor per push-in terminal.
 NOTE: If, nevertheless, two stranded wires are to be connected to a single push-in terminal, twin wire end ferrules must be used.

Table 7. EAGLEHAWK NX push-in terminal wiring specifications

plug gauge	0.2 1.50 mm ²
solid conductor H05(07) V-K	0.2 1.50 mm ²
stranded conductor H05(07) V-K	0.2 1.50 mm ²
stranded conductor with wire end ferrules (w/o plastic collar)	0.2 1.50 mm ²
stripping length	10.0 +1.0 mm

Terminal Assignment

Table 8. Terminal assignment

	1				
terminal no.	signal	Description	CLNXEHSERIES14xxx	CLNXEHSERIES26xxx	CLNXEHSERIES00xxx
1	24V-0	supply voltage (GND), int. connected with term. 31 and system GND (term. 19+37)	X	X	X
2	24V~	supply voltage (24V)	Χ	Χ	Χ
3,4	-	not used	-	-	-
5	BO1	Binary output 1. N.O. relay contact switching input power connected to terminal 8	-	Χ	=
6	BO2	Binary output 2. N.O. relay contact switching input power connected to terminal 8	-	X	-
7	BO3	Binary output 3. N.O. relay contact switching input power connected to terminal 8	-	Х	-
8	IN1,2,3	Common relay contact for BO1, BO2, and BO3	-	X	-
9	IN4	Relay contact for BO4	Х	Х	-
10	BO4	Binary output 4. N.O. relay contact switching input power connected to terminal 9	Х	Х	-
11	BO5	Binary output 5. N.O. relay contact switching input power connected to terminal 12	Х	Х	-
12	IN5	Relay contact for BO5	Х	Χ	-
13	IN6	Relay contact for BO6	Х	Χ	-
14	BO6	Binary output 6. N.O. relay contact switching input power connected to terminal 13	Х	Χ	-
15	BO7	Binary output 7. N.O. relay contact switching input power connected to terminal 16	Χ	Χ	-
16	IN7	Relay contact for BO7	Х	Х	-
17	IN8	Relay contact for BO8	-	Χ	-
18	BO8	Binary output 8. N.O. relay contact switching input power connected to terminal 17	-	Χ	-
19	GND	Ground terminal (see NOTE below)	Х	Χ	-
20	AO1	Analog output 1	Х	Х	_
20	AO1 AO2	Analog output 1 Analog output 2	X	X	-
21	AO2	Analog output 2	X X -	Х	-
21 22	AO2 AO3	Analog output 2 Analog output 3	X	X	
21 22 23	AO2 AO3 AO4	Analog output 2 Analog output 3 Analog output 4	- -	X X X	-
21 22 23 24	AO2 AO3 AO4 GND-1	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated)	- - X	X X X	- - X
21 22 23 24 25	AO2 AO3 AO4 GND-1 485-1+	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated)	X - - X X	X X X X	- - X X
21 22 23 24 25 26	AO2 AO3 AO4 GND-1	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated)	X X X X	X X X X	- X X X
21 22 23 24 25 26 27,28	AO2 AO3 AO4 GND-1 485-1+ 485-1-	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used	X - - X X X	X X X X X X	- X X X
21 22 23 24 25 26 27,28	AO2 AO3 AO4 GND-1 485-1+ 485-1-	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated)	X X X X X X X X	X X X X X X	- X X X X
21 22 23 24 25 26 27,28 29 30	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2+ 485-2-	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated)	X X X X X X X X	X X X X X X	- X X X X
21 22 23 24 25 26 27,28 29 30 31	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2+ 485-2- GND-2	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37)	X X X X X X X X	X X X X X X	- X X X X
21 22 23 24 25 26 27,28 29 30 31	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- 485-2- GND-2	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used	X X X X X X X X X X X X X X X X X X	X X X X X X X X	- X X X X
21 22 23 24 25 26 27,28 29 30 31 32	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2+ 485-2- GND-2 -	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer)	X - X X X X X X X X X X X X X X X X X X	X X X X X X X X	- X X X X X X X X
21 22 23 24 25 26 27,28 29 30 31 32 33 34	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- GND-2 - BI1 BI2	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) "-" signal for RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer) Binary input 2 (static dry contact) / pulse counter (fast totalizer)	X - X X X X X X X X X X X X X X X X X X	X X X X X X X X X	- X X X X X X X
21 22 23 24 25 26 27,28 29 30 31 32 33 34 35	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- GND-2 - BI1 BI2 BI3	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) "-" signal for RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer) Binary input 3 (static dry contact) / pulse counter (fast totalizer) Binary input 3 (static dry contact) / pulse counter (fast totalizer)	X X X X X X X X X X X X X X X X X X	X X X X X X X X X X X X	- X X X X X X X X
21 22 23 24 25 26 27,28 29 30 31 32 33 34 35 36	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- GND-2 - BI1 BI2 BI3 BI4	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer) Binary input 3 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer)	X X X X X X X X X X X X X X X X X X	X X X X X X X X X X X	- X X X X X X X
21 22 23 24 25 26 27,28 29 30 31 32 33 34 35 36 37	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- GND-2 - BI1 BI2 BI3 BI4 GND	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer) Binary input 3 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Ground terminal (see NOTE below)	X X X X X X X X X X X X X X X X X X	X X X X X X X X X X X X	- X X X X X X X
21 22 23 24 25 26 27,28 29 30 31 32 33 34 35 36 37	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- GND-2 - BI1 BI2 BI3 BI4 GND	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer) Binary input 2 (static dry contact) / pulse counter (fast totalizer) Binary input 3 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Ground terminal (see NOTE below) Universal input 9 (for NTC10kΩ / NTC20kΩ / 010 V / slow BI)	X X X X X X X X X X X X X X X X X X	X X X X X X X X X X X X X X	- X X X X X X X
21 22 23 24 25 26 27,28 29 30 31 32 33 34 35 36 37 38	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- GND-2 - BI1 BI2 BI3 BI4 GND UI9	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer) Binary input 2 (static dry contact) / pulse counter (fast totalizer) Binary input 3 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Ground terminal (see NOTE below) Universal input 9 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 10 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI)	X	X X X X X X X X X X X X X X X X	- X X X X X X X
21 22 23 24 25 26 27,28 29 30 31 32 33 34 35 36 37 38 39 40	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- GND-2 - BI1 BI2 BI3 BI4 GND UI9 UI10 UI1	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer) Binary input 2 (static dry contact) / pulse counter (fast totalizer) Binary input 3 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Ground terminal (see NOTE below) Universal input 9 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 10 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI)	X	X X X X X X X X X X X X X X X X	- X X X X X X X
21 22 23 24 25 26 27,28 29 30 31 32 33 34 35 36 37 38 39 40 41	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- GND-2 - BI1 BI2 BI3 BI4 GND UI9 UI10 UI1 UI2	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer) Binary input 2 (static dry contact) / pulse counter (fast totalizer) Binary input 3 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Ground terminal (see NOTE below) Universal input 9 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 1 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 1 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 2 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI)	X	X X X X X X X X X X X X X X	- X X X X X X X
21 22 23 24 25 26 27,28 29 30 31 32 33 34 35 36 37 38 39 40 41 42	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- GND-2 - BI1 BI2 BI3 BI4 GND UI9 UI10 UI1 UI2 UI3	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer) Binary input 2 (static dry contact) / pulse counter (fast totalizer) Binary input 3 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Ground terminal (see NOTE below) Universal input 9 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 10 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 1 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 2 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 3 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI)	X	X X X X X X X X X X X X X X	- X X X X X X X
21 22 23 24 25 26 27,28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- GND-2 - BI1 BI2 BI3 BI4 GND UI9 UI10 UI1 UI2 UI3 UI4	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "+" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer) Binary input 2 (static dry contact) / pulse counter (fast totalizer) Binary input 3 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Ground terminal (see NOTE below) Universal input 9 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 10 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 2 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 3 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 3 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 3 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 4 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI)	X	X X X X X X X X X X X X X X	- X X X X X X X
21 22 23 24 25 26 27,28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- GND-2 - BI1 BI2 BI3 BI4 GND UI9 UI10 UI1 UI2 UI3 UI4 UI5	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "-" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer) Binary input 2 (static dry contact) / pulse counter (fast totalizer) Binary input 3 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Ground terminal (see NOTE below) Universal input 9 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 1 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 2 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 3 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 4 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 3 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 4 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 5 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI)	X	X X X X X X X X X X X X X X X X X X X	- X X X X X X X X X
21 22 23 24 25 26 27,28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44 44	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- GND-2 - BI1 BI2 BI3 BI4 GND UI9 UI10 UI1 UI2 UI3 UI4 UI5 UI6	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "-" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "-" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer) Binary input 2 (static dry contact) / pulse counter (fast totalizer) Binary input 3 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Ground terminal (see NOTE below) Universal input 9 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 1 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 2 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 3 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 4 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 5 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 5 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 5 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI)	X	X X X X X X X X X X X X X X X X X X X	- X X X X X X X X X
21 22 23 24 25 26 27,28 29 30 31 32 33 34 35 36 37 38 39 40 41 42 43 44	AO2 AO3 AO4 GND-1 485-1+ 485-1- 485-2- GND-2 - BI1 BI2 BI3 BI4 GND UI9 UI10 UI1 UI2 UI3 UI4 UI5	Analog output 2 Analog output 3 Analog output 4 ref. GND of RS485-1 (isolated) "-" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) "-" signal for RS485-1 (isolated) not used "+" signal for RS485-2 (non-isolated) "-" signal for RS485-2 (non-isolated) ref. GND of RS485-2, int. conn. with 24V-0 (term. 1) and system GND (term. 19+37) not used Binary input 1 (static dry contact) / pulse counter (fast totalizer) Binary input 2 (static dry contact) / pulse counter (fast totalizer) Binary input 3 (static dry contact) / pulse counter (fast totalizer) Binary input 4 (static dry contact) / pulse counter (fast totalizer) Ground terminal (see NOTE below) Universal input 9 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 1 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 2 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 3 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 4 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 3 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 4 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI) Universal input 5 (for NTC10k Ω / NTC20k Ω / 010 V / slow BI)	X	X X X X X X X X X X X X X X X X X X X	- X X X X X X X X

NOTE: All AOs, UIs, and BIs share the same ground potential. It is thus possible to connect just one combined GND signal for all AOs, UIs, and BIs. Auxiliary terminals may be used if needed.

Power Supply Powering EAGLEHAWK NX

Power is supplied via a removable terminal plug (attached to terminals 1 and 2).

The power supply of the EAGLEHAWK NX controller must conform to Safety Class II. To reduce overall current consumption, the EAGLEHAWK NX can be powered by a switch power supply (rather than by a transformer). See also Table 2 on pg. 3.

NOTE: Due to the risk of short-circuiting (see Fig. 24), it is strongly recommended that the EAGLEHAWK NX controller be supplied with power from a dedicated transformer. However, if the EAGLEHAWK NX controller is to be supplied by the same transformer powering other controllers or devices (e.g., the PW M-Bus Adapter), care must be taken to ensure that correct polarity is observed.

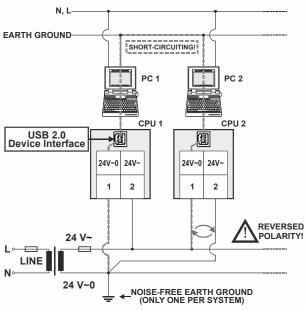


Fig. 24. Incorrect polarity → SHORT-CIRCUITING!

Transformer Data

In Europe, if the EAGLEHAWK NX is powered by transformers, then such transformers must be safety isolating transformers conforming to IEC61558-2-6. In the U.S. and Canada, if the EAGLEHAWK NX is powered by transformers, then such transformers must be NEC Class-2 transformers.

Table 9, 1450 series transformers data

part # 1450 7287	primary side	secondary side
-001	120 VAC	24 VAC, 50 VA
-002	120 VAC	2 x 24 VAC, 40 VA, 100 VA from separate transformer
-003	120 VAC	24 VAC, 100 VA, 24 VDC, 600 mA
-004	240/220 VAC	24 VAC, 50 VA
-005	240/220 VAC	2 x 24 VAC, 40 VA, 100 VA from separate transformer
-006	240/220 VAC	24 VAC, 100 VA, 24 VDC, 600 mA

Table 10. Overview of CRT Series AC/DC current

transformer	primary side	max. AC current	max. DC current			
CRT 2	230 VAC	2 A	500 mA			
CRT 6	230 VAC	6 A	1300 mA			
CRT 12	230 VAC	12 A	2500 mA			

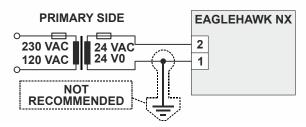


Fig. 25. Connection of EAGLEHAWK NX controller

RIN-APU24

The RIN-APU24 Uninterruptable Power Supply can be directly wired to an EAGLEHAWK NX controller.

See RIN-APU24 Uninterruptable Power Supply – Mounting Instructions (EN0B-0382GE51) for a detailed wiring diagram.

Powering Panel Bus I/O Modules and Field Devices

The EAGLEHAWK NX, Panel Bus I/O modules, and field devices can be powered by either separate transformers (see Fig. 27, and Fig. 28) or by the same transformer (see Fig. 29 on pg. 24).

NOTE: Use a min. distance of 10 cm between power cables and 0...10 V / sensor cables in order to prevent signal disturbances on the 0...10 V / sensor cables. See also section "Addressing Panel Bus I/O Modules" on page 38.

Powering Field Devices and EAGLEHAWK NX via Separate Transformers

- 24 V actuator connected to separate transformer.
- Field device located max. 400 m from EAGLEHAWK NX.

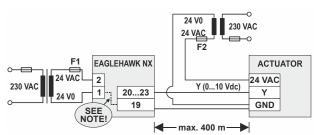


Fig. 26. Power supply of EAGLEHAWK NX and field devices by separate transformer

NOTE: The internal connection from 24 V0 to GND shown here is designed for max. 200 mA.

Powering Field Devices and Panel Bus I/O Module via Separate Transformers

- 24 V actuator connected to, e.g., an analog output module.
- Field device located 100 ... 400 m from the analog output module.

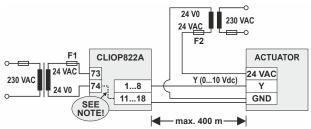


Fig. 27. Power supply via a separate transformer

NOTE: The internal connection from 24 V0 to GND shown here is designed for max. 200 mA.

Powering Field Devices via Panel Bus I/O Module

- 24 V actuator connected to, e.g., an analog output module.
- Field device located max. 100 m from the analog output module.

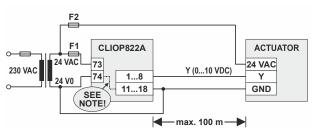


Fig. 28. Power supply via Panel Bus I/O Module

NOTE: The internal connection from 24 V0 to GND shown here is designed for max. 200 mA.

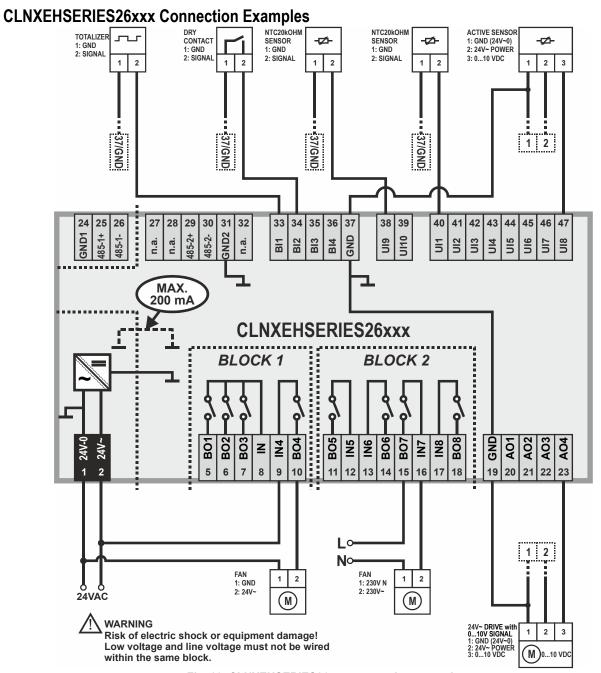


Fig. 29. CLNXEHSERIES26xxx connection example

For fusing specifications see section "Fusing Specifications" on page 20.

NOTE: Use a min. distance of 10 cm between power cables and 0...10 V / sensor cables in order to prevent signal disturbances on the 0...10 V / sensor cables.

NOTE: The internal connection from 24 V0 to GND shown here is designed for max. 200 mA.

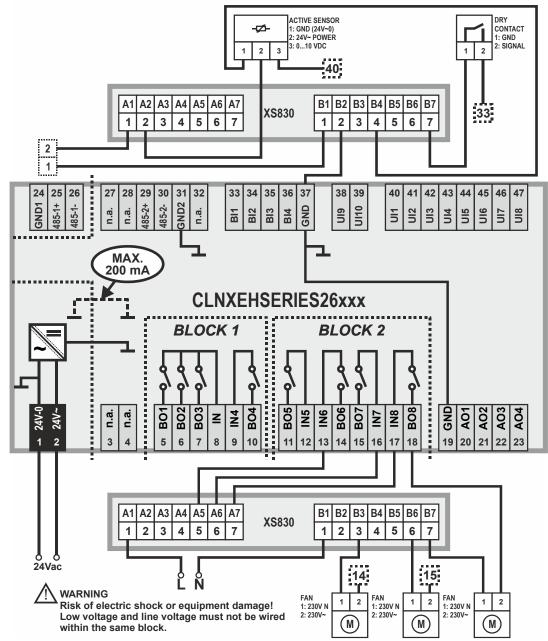


Fig. 30. CLNXEHSERIES26xxx connection example (with two XS830 Auxiliary Terminal Packages)

The XS830 and XS831 Auxiliary Terminal Packages are optional accessories which can be mounted onto the top and/or bottom of the EAGLEHAWK NX controller in order to equip them with additional terminals for the connection of, e.g., shields, sensors, GND, N, 230 V, or 24 V (but not earth!).

NOTE: Use a min. distance of 10 cm between power cables and 0...10 V / sensor cables in order to prevent signal disturbances on the 0...10 V / sensor cables.

NOTE: The internal connection from 24 V0 to GND shown here is designed for max. 200 mA.

Internal I/Os of the EAGLEHAWK NX

The CLNXEHSERIES00xxx is not equipped with inputs or outputs. The following sub-sections thus apply only to the CLNXEHSERIES14xxx and CLNXEHSERIES26xxx.

Universal Inputs

The CLNXEHSERIES26xxx is equipped with ten (CLNXEHSERIES14xxx: four) universal inputs (UIs) configurable (in COACH NX).

For information on the accuracy of the sensor inputs, their differential measurement error, the characteristics (i.e., resistances and resultant voltages in dependence upon temperature) of the various different sensor types which can be connected to them, and on the thresholds at which sensor failures are recognized, see section "Appendix 2" on pg. 57.

Table 11. Specifications of UIs

Table 11. Specifications of UIS		
criteria	value	
voltage input	UI1-UI10: 0 10 VDC with pull-up resistor (default)	
	UI1-UI8: 010 VDC w/o pull-up resistor	
	UI1-UI8: 210 VDC w/o pull-up resistor	
current input	UI1-UI10: 0 10 VDC w/o pull-up resistor, external 499Ω resistor required to measure 020 mA	
	UI1-UI8: 210 VDC w/o pull-up resistor, external 499Ω resistor required to measure 420 mA	
supported	• NTC10kΩ (-30+100 °C)	
sensor types	• NTC20kΩ (-50+150 °C)	
typoo	Slow binary input (static, dry-contact), 0.4 Hz	
resolution	12-bit resolution	
accuracy	±75 mV (0 10 V)	
protection	against short-circuiting, 24 VAC	

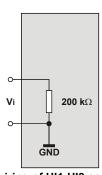


Fig. 31 Internal wiring of UI1-UI8 configured for voltage input (without pull-up resistor)

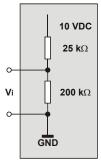


Fig. 32. Internal wiring of UI1-UI10 configured for input from NTC10k Ω / NTC20k Ω / voltage input (with pull-up resistor)

Slow Binary Input Specifications

When configured as slow binary inputs, the universal inputs of the EAGLEHAWK NX have the following specifications:

open contact	≥ 100 kΩ
closed contact	≤ 100 Ω

The polarity (normal = N.O. contact or reverse = N.C. contact) configuration defines if a logical 1 or a logical 0 is detected for a closed contact. This is done by selecting (in COACH NX) one of the following options:

normal (default)	closed external contact →	state=1
mormar (deradit)	open external contact →	state=0
	closed external contact \rightarrow	state=0
reverse	open external contact →	state=1

Pulse Counter Specifications

Using COACH NX, the universal inputs of the EAGLEHAWK NX can be configured as pulse counters (totalizers).

If the duty cycle is 50% / 50%, the pulse counter supports up to 0.4 Hz. Counting is done on the rising edge.

Table 12. Uls of EAGLEHAWK NX configured as slow BIs

frequency	max. 0.4 Hz
pulse ON	min. 1.25 s
pulse OFF	min. 1.25 s
bounce	max. 50 ms

Analog Outputs

The CLNXEHSERIES26xxx is equipped with four (CLNXEHSERIES14xxx: two) analog outputs (AOs).

In the event of an application stop (e.g., during application download), the analog outputs assume the safety positions configured in COACH NX.

The analog outputs can be configured in COACH NX as binary outputs (with an output of 0 V or 10 V, as the case may be).

Table 13. Specifications of AOs

rable for oppositions of field		
criteria	value	
	• 010 V (default)	
output type	• 210 V	
max. output range	0 11 VDC (1 mA)	
min. resolution	8 bit	
min. accuracy	± 150 mV	
max. wire length	400 m	
wire cross section	See Table 7 on pg. 20.	
protection	against short-circuiting, 24 VAC	

Binary Inputs / Pulse Counters

Both the CLNXEHSERIES26xxx and the CLNXEHSERIES14xxx are equipped with four binary inputs (static dry-contact inputs) / pulse counters (fast totalizers).

Table 14. Specifications of Bls

rabio i ii opcomoationo di bio		
criteria	value	
input type	binary input (static dry-contact)pulse counter (fast totalizer)	
current rating (closed input)	2 mA	
open contact voltage	24 VDC	
protection	against short-circuiting, 24 VAC	

Binary Input Specifications

The binary inputs of the EAGLEHAWK NX are static drycontact inputs. This reduces the wiring effort, as it is then not necessary to distribute an auxiliary voltage signal.

open contact	≥ 3000 Ω (24 VDC on BI terminal)
closed contact	≤ 500 Ω (short-circuit current: 2.0 mA)

The polarity (normal = N.O. contact or reverse = N.C. contact) configuration defines if a logical 1 or a logical 0 is detected for a closed contact. This is done by selecting (in COACH NX) one of the following options:

normal (default)	closed external contact \rightarrow	state=1
	open external contact →	state=0
roverse	closed external contact →	state=0
reverse	open external contact →	state=1

Pulse Counter Specifications

Using COACH NX, the binary inputs of the EAGLEHAWK NX can be configured as pulse counters (fast totalizers) for operation in conjunction with devices equipped with an open collector output.

If the duty cycle is 50% / 50%, the pulse counter supports up to 15 Hz. Counting is done on the rising edge.

Table 15. Bls of EAGLEHAWK NX configured as fast totalizers

frequency	max. 15 Hz
pulse ON	min. 25 ms
pulse OFF	min. 25 ms
bounce	max. 5 ms

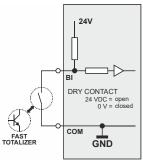


Fig. 33. Internal wiring of BI

Binary Outputs

The EAGLEHAWK NX features eight (CLNXEHSERIES26xxx) or four (CLNXEHSERIES14xxx) binary outputs arranged in two blocks (BO1...4 and BO5...8, respectively).



⚠ WARNING

Risk of electric shock or equipment damage! Low voltage and line voltage must not be wired within the same block.

In the event of an application stop (e.g., during application download), the binary outputs assume the safety positions configured in COACH NX.

The polarity (normal = N.O. contact or reverse = N.C. contact) configuration defines if a relay is open or closed, depending upon whether there is a logical 1 or a logical 0. This is done by selecting (in COACH NX) one of the following options:

n a mas al (alafa ult)	state=1 →	relay contact is closed
normal (default)	state=0 →	relay contact is opened
reverse	state=0 →	relay contact is closed
	state=1 →	relay contact is opened

Table 16. Relay specifications of the EAGLEHAWK NX

	block 1		block 2
	BO13	BO4	BO58
contact volt. AC	5253 V	5253 V	5253 V
contact volt. DC	530 V	2030 V	530 V
max. contact cur- rent AC (resistive)	3 A	10 A	3 A
max. contact cur- rent AC (induct.)	0.3 A*	10 A	0.3 A*
max. contact cur- rent AC (induct.)	2 A**	10 A	2 A**
max. contact cur- rent DC	3 A	7 A	3 A
min. load	100 mA / 5 VDC	40 mA / 24 VDC	100 mA / 5 VDC
* typically 250,000 cycles; ** typically 50,000 cycles			

NOTE: The total max. sum load for all binary outputs

(BO1...8) equals 14 A.

NOTE: Binary output 4 supports the switching of high in-

rush currents (e.g., motors, incandescent lights, etc.). The max. allowed switch current is 80 A for a

duration of max. 20 ms.

ENGINEERING, COMMISSIONING

Please refer also to CentraLine NX BACnet Utilities Driver - User Guide (Product Literature No.: EN2Z-1020GE51) for detailed information.

Required Preparations

In order to access (with a laptop or PC) the EAGLEHAWK NX controller via Ethernet/IP for the first time, the default passwords are used. For IP connections, you may employ any one of the following two options:

Option 1: USB 2.0 Device (recommended)

This USB 2.0 Device interface is the recommended interface for downloading applications and firmware via COACH NX. An "A-Male to B-Male" USB cable is required.

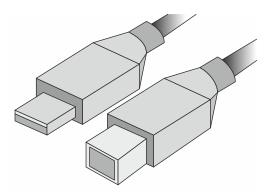


Fig. 34. A-male to B-male USB cable

For access via USB, the EAGLEHAWK NX controller has a permanent default IP address 192.168.255.241. Your PC's IP address must match the EAGLEHAWK NX controller's default IP address subnet: We recommend using DHCP or "Obtain an automatic IP address".

Option 2: Standard Ethernet Interface

The default IP address of Ethernet interface 1 is: 192.168.200.20

and the default IP address of Ethernet interface 2 is: 192.168.201.20

In any case, your PC's IP address must match the EAGLEHAWK NX controller's default IP address subnet (255.255.255.0).

Behavior of Outputs during Download

Table 17. Behavior of outputs during firmware download / application download

approximate de management			
analog, binary, and floating outputs	output behavior during firmware download	output behavior during application download	
outputs of Panel I/O modules (CLIOP82x)	As soon as "receive heartbeat" (the value of which CANNOT be altered using COACH NX) expires, outputs go to safety position.	As soon as "receive heartbeat" (the value of which CANNOT be altered using COACH NX) expires, outputs go to safety position.	
outputs of LONWORKS I/O modules (CLIOL82x)	As soon as "receive heartbeat" (the value of which can be altered using COACH NX) expires, outputs go to safety position.	As soon as "receive heartbeat" (the value of which can be altered using COACH NX) expires, outputs go to safety position.	
onboard I/Os	After the configured time-out, go to safety position.	After the configured time-out, go to safety position.	

NOTE: These behaviors were determined using a test application with a cycle time of 10 seconds. A value update was triggered every 10 seconds.

EXTRA PARTS

Table 18. Extra parts

	order no.	description
	XS830	Set of ten terminals. Each package consists of two groups of nine internally connected push-in terminals, for distributing signals / power.
	XS831	Set of ten terminals. Each package consists of two groups of four pairs of push-in terminals (each with a 499 Ω resistor), for converting 020 mA signals into 010 VDC signals, and one push-in ground terminal per group.
1°2	TPU-11-01	Removable terminal plugs, push-in type; complete set of 3 plugs (for terminals 1, 2, 24-32); for the CLNXEHSERIES00xxx.
	TPU-45-01	Removable terminal plugs, push-in type; complete set of 9 plugs (for terminals 1 - 47); for the CLNXEHSERIES14xxx and CLNXEHSERIES26xxx.
000000000000000000000000000000000000000	MVC-80-AC1	Terminal cover (color: RAL9011); package of ten.
	MVC-80-AC2	Front door mounting accessory (color: RAL9011); package of 10.
THE PERFERENCE OF THE PERFECT OF THE	MVC-40-AC3	Strain relief; package of ten.

SOFTWARE LICENSES AND UPGRADES

EAGLEHAWK NX Basic Licenses

Every EAGLEHAWK NX controller must have a basic license. Select one of the options listed in the table below.

Table 19. EAGLEHAWK NX Basic licenses

CentraLine order no.	Contents	Comments
CLNXEH-BASLIC	100 global points; 255 Panel Bus points; initial SMA	Onboard IOs are counted in the Panel Bus license.
CLNXEH-BASLIC-5Y	100 global points; 255 Panel Bus points; 5-year SMA	Onboard IOs are counted in the Panel Bus license.
CLNXEH-BASSPLIC	50 global points; 100 Panel Bus points; initial SMA	Onboard IOs are counted in the Panel Bus license.
CLNXEH-BASSMLIC	100 global points; initial SMA	Does not contain Panel Bus. Onboard IOs are part of
CLNXEH-BASROOMLIC*	100 global points; no initial SMA	the global capacity. As soon as a Panel Bus license is added, the onboard IOs will be switched to Panel Bus.
CLNXEH-BASLIC5005Y	500 global points; 100 Panel Bus points; 5-year SMA	Onboard IOs are counted in the Panel Bus license.
CLNXEH-DEMO	Demo license	1-year demo license; 25,000 global points; 10,000 history extensions; unlimited Panel Bus points

^{*}Will be phased out in January 2021.

The basic licenses (but not the demo license) can be upgraded. See the following sections "EAGLEHAWK NX Point Upgrade Licenses" and "EAGLEHAWK NX SMA Licenses."

EAGLEHAWK NX Point Upgrade Licenses

EAGLEHAWK NX basic licenses (but not the CLNXEH-BASROOMLIC and demo license) can be upgraded with any of the following upgrade licenses in Table 6. For old EAGLEHAWK NX basic licenses and the CLNXEH-BASROOMLIC see Table 7.

NOTE: The upgrade licenses for new and old licenses are not compatible! The license models CLNXEHLIC and CLNXEHROOMLIC can therefore be upgraded only with the options listed in Table 7.

Table 20. EAGLEHAWK NX Point upgrade licenses for CLNXEH-BASLIC, CLNXEH-BASLIC-5Y, CLNXEH-BASSPLIC, CLNXEH-BASLIC5005Y

CentraLine order no.	Description
CLNXEH-DEVICE-UP-1	EAGLEHAWK NX plus 50 global points upgrade
CLNXEH-DEVICE-UP-2	EAGLEHAWK NX plus 100 global points upgrade
CLNXEH-DEVICE-UP10	EAGLEHAWK NX plus 500 global points upgrade
CLNXEH-DEVICE-UP25	EAGLEHAWK NX plus 1,250 global points upgrade
CLNXEH-DEVICE-UP50	EAGLEHAWK NX plus 2,500 global points upgrade
CLNXEHPB100UP	Upgrade license for 102 Panel Bus points
CLNXEHPB255UP	Upgrade license for 255 Panel Bus points

Table 21. EAGLEHAWK NX Point upgrade licenses for CLNXEH-BASROOMLIC (model CLNXEHROOMLIC) and EAGLEHAWK controllers delivered till December 2019 (model CLNXEHLIC)

CentraLine order no.	Description
CLNXEH-OLDLIC-UP-1	EAGLEHAWK NX plus 50 global points upgrade
CLNXEH-OLDLIC-UP-2	EAGLEHAWK NX plus 100 global points upgrade
CLNXEH-OLDLIC-UP10	EAGLEHAWK NX plus 500 global points upgrade
CLNXEH-OLDLIC-UP25	EAGLEHAWK NX plus 1,250 global points upgrade
CLNXEH-OLDLIC-UP50	EAGLEHAWK NX plus 2,500 global points upgrade
CLNXEHPB100UP	Upgrade license for 102 Panel Bus points
CLNXEHPB255UP	Upgrade license for 255 Panel Bus points
CLNXEHRBAC250UP*	Upgrade license for 250 BACnet room points
CLNXEHRLON250UP*	Upgrade license for 250 LONWORKS room points

EAGLEHAWK NX controllers licensed with CLNXEHLIC and CLNXEH-BASROOMLIC are the only licenses compatible with the BACnet license (CLNXEHRBAC250UPLIC) and the LonWorks license (CLNXEHRLON250UPLIC). We have stopped delivering licensed controllers with CLNXEHLIC in January 2020. CLNXEH-BASROOMLIC will be phased out in January 2021. All the licenses in your software stock can still be used according to the above assignment rules.

EAGLEHAWK NX Upgrade Licenses

The following licenses can be assigned to the EAGLEHAWK NX only once.

Table 22. EAGLEHAWK NX upgrade licenses

CentraLine order no.	Description
CLNX-DR-MFID	NX FIDELIO DRIVER
CLNX-DR-SMS-ALM	NX SMS DRIVER

EAGLEHAWK NX SMA Licenses

The EAGLEHAWK NX basic licenses CLNXEH-BASLIC, CLNXEH-BASLIC-5Y, CLNXEH-BASSPLIC, CLNXEH-BASSMLIC, CLNXEH-BASLIC5005Y can be upgraded with any of the following SMA licenses.

The number of points is taken into consideration at the moment of licensing. If you have a valid SMA and you upgrade with a number of points exceeding the SMA, the licenses will run until your SMA expires. If you extend your SMA after expiration, you will have to buy the SMA to reflect the new number of global points.

See following table.

CLNXEH-BASROOMLIC (model CLNXEHROOMLIC) and EAGLEHAWK controllers delivered till December 2019 (model CLNXEHLIC) can be upgraded only with SMA starting from CLNX-SMA-0005-1YR and continuing to CLNX-SMA-0100-5YR.

Table 23. EAGLEHAWK NX SMA licenses

CentraLine order no.	Description	Comments
CLNX-SMA-0001-1YR	1YR S/W UPDATE FOR 000 – 049 PTS	Available only for CLNXEH-BASLIC,
CLNX-SMA-0001-3YR	3YR S/W UPDATE FOR 000 – 049 PTS	CLNXEH-BASLIC-5Y, CLNXEH-
CLNX-SMA-0001-5YR	5YR S/W UPDATE FOR 000 – 049 PTS	BASSPLIC, CLNXEH-BASSMLIC, CLNXEH-BASLIC5005Y
CLNX-SMA-0002-1YR	1YR S/W UPDATE FOR 50 – 100 PTS	CEIVAETI-BAGEICO0001
CLNX-SMA-0002-3YR	3YR S/W UPDATE FOR 50 – 100 PTS	
CLNX-SMA-0002-5YR	5YR S/W UPDATE FOR 50 – 100 PTS	
CLNX-SMA-0005-1YR	1YR S/W UPDATE FOR 100 – 499 PTS	Available for all basic licenses above
CLNX-SMA-0005-3YR	3YR S/W UPDATE FOR 100 – 499 PTS	and CLNXEH-BASROOMLIC (model
CLNX-SMA-0005-5YR	5YR S/W UPDATE FOR 100 – 499 PTS	CLNXEHROOMLIC) and EAGLEHAWK controllers delivered till December 2019
CLNX-SMA-0010-1YR	1YR S/W UPDATE FOR 500 – 1249 PTS	(model CLNXEHLIC)
CLNX-SMA-0010-3YR	3YR S/W UPDATE FOR 500 – 1249 PTS	(,
CLNX-SMA-0010-5YR	5YR S/W UPDATE FOR 500 – 1249 PTS	
CLNX-SMA-0025-1YR	1YR S/W UPDATE FOR 1250 – 4999 PTS	
CLNX-SMA-0025-3YR	3YR S/W UPDATE FOR 1250 – 4999 PTS	
CLNX-SMA-0025-5YR	5YR S/W UPDATE FOR 1250 – 4999 PTS	
CLNX-SMA-0100-1YR	1YR S/W UPDATE FOR 5000 – 9999 PTS	
CLNX-SMA-0100-3YR	3YR S/W UPDATE FOR 5000 – 9999 PTS	
CLNX-SMA-0100-5YR	5YR S/W UPDATE FOR 5000 – 9999 PTS	

EAGLEHAWK NX Energy Manager License

The EAGLEHAWK NX Energy Manager license is not yet supported by the new online licensing portal. Instead, the licensing must be obtained via Niagara Central.

Table 24. EAGLEHAWK NX Energy Manager license

CentraLine order no.	Description
CLNXEMC12	ENERGYVISION BASE LIC 12 METER PTS

EAGLEHAWK NX E-Signature, Camera-, Niagara Analytics, JSON, and Cloud Drivers

All of the following licenses are supported by the online licensing portal.

Table 25. Licenses supported by the online licensing portal

CentraLine order no.	License key	Description
CLNX-C-ESIG-250	ESIGN-EC-N4-250	E-SIGNATURE 250 SECURED POINTS
CLNX-C-ESIG-UNL	ESIGN-EC-N4-UNL	E-SIGNATURE UNLIMITED SECURED POINTS
CLNX-C-ESIG-UP250	ESIGN-EC-N4-UP-250	E-SIGNATURE 250 SECURED POINT UPGRADE
CLNX-C-NA-100	NA-EC-N4-100	ANALYTICS FOR 100 POINTS EHNX; HAWK8
CLNX-C-NA-250	NA-EC-N4-250	ANALYTICS FOR 250 POINTS EHNX; HAWK8
CLNX-C-NA-500	NA-EC-N4-500	ANALYTICS FOR 500 POINTS EHNX; HAWK8
CLNX-C-NA-1000	NA-EC-N4-1000	ANALYTICS FOR 1000 POINTS EHNX; HAWK8
CLNX-C-DR-AXIS-8	DR-AXIS-8	AXIS 8 CAMERA DRIVER EHNX; HAWK8
CLNX-C-DR-MLS-8	DR-MLS-8	MILESTONE 8 CAMERA DRIVER EHNX; HAWK8
CLNX-C-DR-JSON	DR-JSON	JSON INTEGRATION EHNX; HAWK8
CLNX-S-NCLOUD-S500	DR-NCLOUD-SEN500	NIAGARA CLOUD SENTIENCE 500 POINTS
CLNX-S-NCLOUDS1000	DR-NCLOUD-SEN1000	NIAGARA CLOUD DRIVER 1000 POINTS
CLNX-S-NCLOUDS2500	DR-NCLOUD-SEN2500	NIAGARA CLOUD DRIVER 2500 POINTS
CLNX-S-NCLOUD-S10K	DR-NCLOUD-SEN10000	NIAGARA CLOUD DRIVER 10000 POINTS

PANEL BUS CONNECTION

The EAGLEHAWK NX controller features two RS485 interfaces to which Panel Bus modules can be connected: RS485-1 (consisting of push-in terminals 24 [GND-1], 25, and 26) and/or RS485-2 (consisting of push-in terminals 29, 30, and 31 [GND-2]).

NOTE: GND-2 is internally connected with 24V-0 (terminal 1)

Overview of Panel Bus I/O Modules

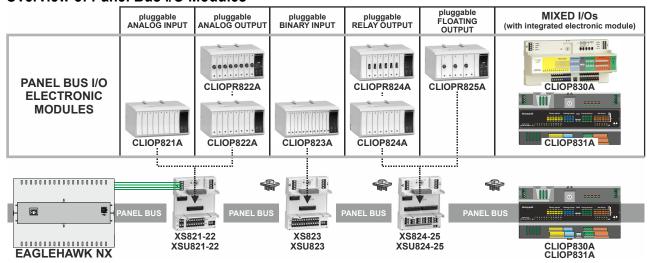


Fig. 35. Overview of Panel Bus I/O Modules

Panel Bus Considerations

- RS485-1 (isolated)
 - Max. Panel Bus length:
 - 40 meters. Any type of cabling and topology (including star and loop topology) possible. No additional end termination permitted.
 - 1200 meters (9.6 78.8 kbps) or 800 meters (115.2 kbps) (see also section "RS485 Standard" on pg. 10).
 Mandatory twisted-pair or telephone cable and daisy chain topology. The EAGLEHAWK NX must be positioned at one end of the Panel Bus, and an end termination (120 Ω) at the other end. Further, the three-position slide switch (see Fig. 14 on pg. 9) must be set to "END."
- RS485-2 (non-isolated)
 - Max. Panel Bus length:
 - 40 meters. Any type of cabling and topology (including star and loop topology) possible. No additional end termination permitted.
 - 1200 meters (9.6 78.8 kbps) or 800 meters (115.2 kbps) (see also section "RS485 Standard" on pg. 10).
 Mandatory twisted-pair or telephone cable and daisy chain topology. The EAGLEHAWK NX controller must be positioned at one end of the Panel Bus, and an end termination (120 Ω) at the other end.
 - Must not extend beyond a single building or building floor
- Max. no. of Panel Bus I/O modules per RS485 interface
 - Max. no. of Panel Bus I/O modules of a given model: 16
 - Total max. no. of Panel Bus I/O modules: 64
- Max. no. of Panel Bus I/O modules per EAGLEHAWK NX
 - Max. no. of Panel Bus I/O modules of a given model: 32
 - Total max. no. of Panel Bus I/O modules: 128
- Max. no. of hardware I/O points per EAGLEHAWK NX: 1000 (given a polling rate of 2 seconds; see also section "Controller Performance" on pg. 52)

Refer to CentraLine I/O Modules - Installation & Commissioning Instructions (EN1Z-0973GE51) for more information about connection, current requirements, power supply, overvoltage protection, cable specifications, fusing, effects of manual overrides, etc. of Panel Bus I/O modules and field devices connected to them.

Connecting Contr. via RS485-1 to Panel Bus

NOTE: When connecting an EAGLEHAWK NX via its RS485-1 to a Panel Bus I/, it is recommended that the slide switch be set to "END."

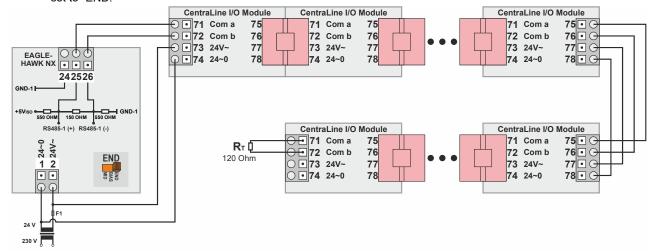


Fig. 36. Connecting an EAGLEHAWK NX controller via its RS485-1 interface to a Panel Bus (single transformer)

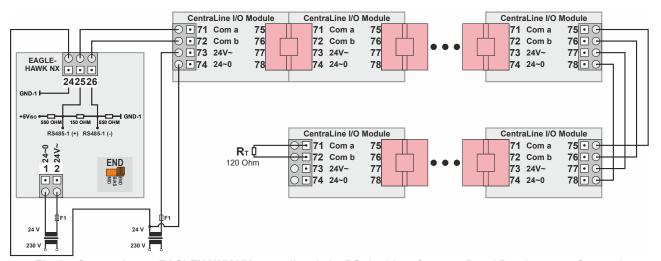


Fig. 37. Connecting an EAGLEHAWK NX controller via its RS485-1 interface to a Panel Bus (two transformers)

Connecting Contr. via RS485-2 to Panel Bus

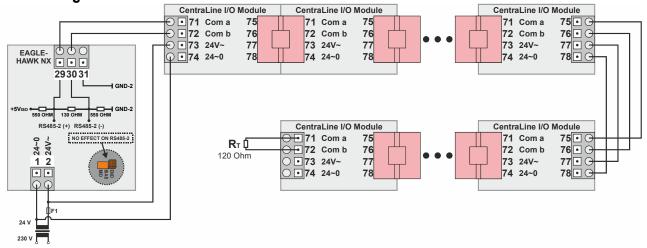


Fig. 38. Connecting an EAGLEHAWK NX controller via its RS485-2 interface to a Panel Bus (single transformer)

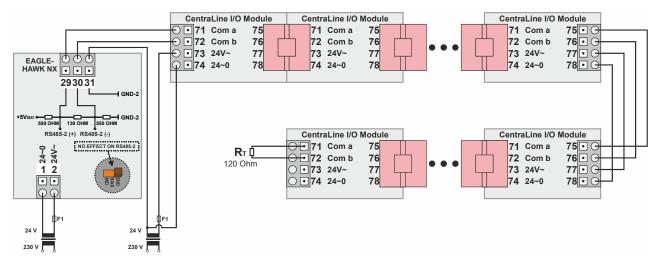


Fig. 39. Connecting an EAGLEHAWK NX controller via its RS485-2 interface to a Panel Bus (two transformers)

Addressing Panel Bus I/O Modules

Each Panel Bus I/O Module must be addressed manually using its HEX switch (S2). The HEX switch setting is defined using the COACH NX engineering tool.

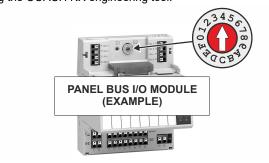


Fig. 40. Location of HEX switch on Panel Bus I/O Module

NOTE: A HEX switch setting of "0" corresponds to an address in COACH NX of "1," a setting of "1" corresponds to an address of "2," and so on.

During commissioning, a max. of 16 Panel Bus I/O Modules of each type (AI, DO, etc.) can be assigned addresses. In doing so, no two modules of the same type (e.g., no two Analog Input Modules, no two Digital Output modules, etc.) may be assigned the same address. See also Fig. 41.

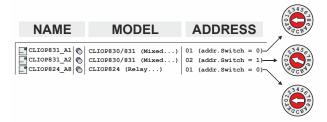


Fig. 41. HEX switch setting and corresponding address

Failing to observe this requirement will cause a "Fail [date] timeout" error message to appear in the "Health" column, and the device status "down" to appear in the "Status" column. This same error message will likewise appear if an address is assigned to a module with which the controller cannot, for any reason (e.g., due to defective wiring, or because the module has not been physically installed, etc.), communicate.

Automatic Updating of Panel Bus I/O Module Firmware

The firmware of the Panel Bus I/O modules is part of the EAGLEHAWK NX firmware. The EAGLEHAWK NX controller will thus automatically update the firmware of the Panel Bus I/O modules as soon as it detects an older version in them.

CleanDist

The number of EAGLEHAWK NX CleanDist files has been enhanced to now *three* CleanDist files. These CleanDist files allow each user to individually clean up the respective EAGLEHAWK NX controller according to his individual requirements.

CleanDist 1:

Deletes station and all of the modules.

CleanDist 2:

Deletes station, modules, system passphrase, username, and password.

Also resets the IP address to its default, i.e., for

Ethernet interface 1: 192.168.200.20, mask 255.255.255.0 and for

Ethernet interface 2: 192.168.201.20, mask 255.255.255.0

CleanDist 3:

Deletes station, modules, system passphrase, username and password, license, and certificates.

Also resets the IP address to its default, i.e., for

Ethernet interface 1: 192.168.200.20, mask 255.255.255.0 and for

Ethernet interface 2: 192.168.201.20, mask 255.255.255.0

Additionally, CleanDist3 will reset the installed firmware to the Factory Firmware Version 4.4.92.2.1.04.1.

Factory Firmware Scope:

The factory firmware allows the engineer to access all engineering tool (COACH NX) versions since 4.4...

This prevents a version conflict between the engineering tool and the controller during commissioning.

The introduction of this basic firmware became necessary because the EAGLEHAWK NX controller cannot be downgraded in terms of firmware.

The basic firmware does not allow a station to be started and must therefore be updated with the appropriate firmware by the Commissioning Wizard. This is the same procedure used with the HAWK 8000 controllers.

Table 26. CleanDist options

Which element	CleanDist	CleanDist	CleanDist
should be deleted?	1	2	3
Station	X	X	X
Module	X	X	Х
System passphrase		Х	Х
User and password	-	Х	Х
IP address	-	Х	Х
License and certificates	-	-	X
Firmware	-	-	X
			\downarrow
			factory
			default

Cable Specifications

Panel Bus I/O Modules

When checking the length of the power supply cable, the connection cables to all Panel Bus I/O Modules must be taken into account.

Table 27. Power supply cable specifications

max. length	3 m (from transformer to final module)	
cross section	min. 0.75 mm² (AWG 18)	

EIA 485 Cable Specifications

The following cable specification is valid for all EIA 485 buses (e.g., Panel Bus, Modbus, and BACnet MS/TP).

Table 28. EIA 485 cable specifications

max. length	1200 meters (9.6 – 78.8 kbps) or 800 meters (115.2 kbps).
cable type	twisted pair, shielded (foil or braided shields are acceptable)
characteristic impedance	100130 Ω
distributed capacitance between conductors	Less than 100 pF per meter (30 pF per foot)
distributed capacitance between conductors and shield	Less than 200 pF per meter (60 pF per foot)

The following cables fulfill this requirement:

- AWG 18;
- shielded, twisted pair cable J-Y-(St)-Y 4 x 2 x 0.8;
- CAT 5,6,7 cable (use only one single pair for one bus);
- Belden 9842 or 9842NH.

Tuning Panel Bus Communication

The default polling interval for all Panel Bus points is set to "normal = 10s". Data from the field is thus updated every 10s. Write commands are sent without time delay.

It is recommended that you update the polling interval of those points requiring more-frequent updating (see Fig. 42). **IMPORTANT**

For EAGLEHAWK NX, the fastest poll rate is 200 milliseconds.

Do NOT set a faster poll rate, as this may overload the CPU in larger systems.

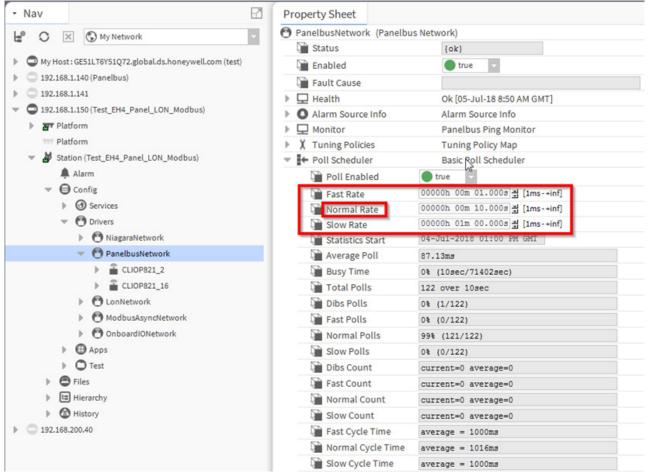


Fig. 42. Editing the standard polling interval in "Poll Scheduler" of Property Sheet of PanelbusNetwork

You can assign different poll intervals to individual points in the Panel Bus Point Discovery Dialog (see Fig. 43).

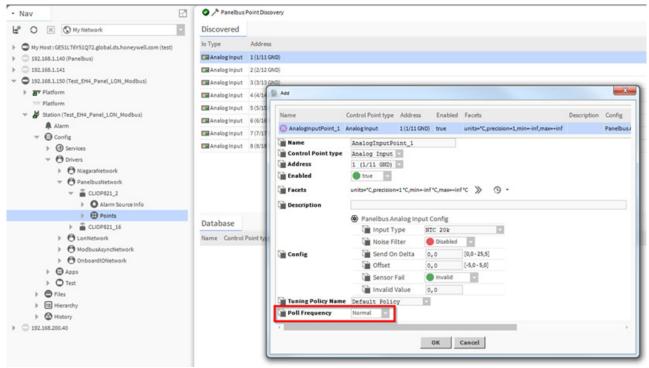


Fig. 43. Assigning different poll intervals to individual points in the Panel Bus Point Discovery Dialog

Field Devices

Depending on the distance from the controller, field devices can be supplied with power by the same transformer used for the Panel Bus I/O Modules, or by a separate transformer, using cables as specified in Table 29.

Table 29. Power / communication cable specifications

	cross-sectional area			
type of signal	≤ 100 m (Fig. 28) single transformer	≤ 400 m (Fig. 27) sep. transformers		
24 VAC power	1.5 mm ² (16 AWG)	not allowed for > 100 m (300 ft)		
010 V signals	0.081 – 2.08 mm ² (28 – 14 AWG)			

For wiring field devices, see section "Powering Panel Bus I/O Modules and Field Devices" on page 23.

Routing Cables to Field Devices

Route low-voltage signal and output cables to field devices separately from mains cables.

Table 30. Minimum distances to power mains cables

cable	min. distance
shielded	10 mm (0.4 in.)
unshielded	100 mm (4 in.)

All low-voltage signal and output cables should be regarded as communication circuits in accordance with VDE 0100 and VDE 0800 (or NEC or other equivalent).

- If the general guidelines for cable routing are observed, it is not necessary to shield field device signal and power supply cables.
- If, for whatever reason, the routing guidelines cannot be observed, the field device signal and power supply cables must be shielded.
 - Shielding of cables leading to field devices must be grounded only at one end.
 - Do not connect the shield to the EAGLEHAWK NX controller.

LONWORKS COMMUNICATIONS

General Information

The EAGLEHAWK NX can be connected to LonWorks networks. This requires the use of an IF-LON (see section "IF-LON" below), which is then plugged into to the EAGLEHAWK NX controller's USB 2.0 Host Interface (see also section "USB 2.0 Host Interface" on pg. 7).

This permits individual EAGLEHAWK NX controllers to be connected / disconnected from the LonWORKS network without disturbing the operation of other devices.

The LonWorks network is insensitive to polarity, eliminating the possibility of installation errors due to miswiring.

Different network configurations (daisy-chain, loop, and star configurations, or any combination thereof) are possible (see also Excel 50/500 LonWorks Mechanisms Interface Description, EN0B-0270GE51).

Connecting to a LONWORKS Network

Do not bundle wires carrying field device signals or LONWORKS communications together with high-voltage power supply or relay cables. Specifically, maintain a min. separation of 3 inches (76 mm) between such cables. Local wiring codes may take precedence over this recommendation.

IMPORTANT

Try to avoid installing in areas of high electromagnetic noise (EMI).

Cable Types

The unit must be wired to the LONWORKS network using either

- level IV 22 AWG (Belden part number 9D220150) or
- plenum-rated level IV 22 AWG (Belden part number 9H2201504) non-shielded, twisted-pair, solid-conductor

When possible, use Honeywell AK3781, AK3782, AK3791, or AK3792 cable (US part numbers). See Excel 50/5000 LonWorks Mechanisms, EN0B-0270GE51, for details, including maximum lengths.

Use wire with a minimum size of 20 AWG (0.5 mm²) and a maximum size of 14 AWG (2.5 mm²).

IF-LON2

Optionally, communication with physical I/O modules, with room and zone controllers, and with CentraLine PANTHER, TIGER, and LION controllers can utilize LonTalk.

The IF-LON is equipped with a free-topology transceiver (FTT10A) for communication (at a data transmission rate of 78 kbps) on LonWorks® networks (using the LonTalk protocol).

The LonWorks network is insensitive to polarity, eliminating the possibility of installation errors due to miswiring. Different network configurations (daisy-chain, loop, and star configurations, or any combination thereof) are possible. See Excel 50/5000 LonWorks Mechanisms (EN0B-0270GE51) for details.



Fig. 44. IF-LON2

See also IF-LON2 – Mounting Instructions (Product Literature no.: MU1B-0545GE51).

Depending upon the chosen network configuration, one or two terminations may be required.

The following LONWORKS termination module is available:

 LONWORKS connection / termination module (mountable on DIN rails and in fuse boxes), order no.: XAL-Term2

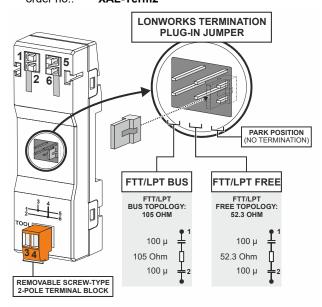


Fig. 45. LonWorks connection and termination module

BACNET MS/TP BUS CONNECTION

The EAGLEHAWK NX controller features two RS485 interfaces to which BACnet MS/TP devices can be connected: RS485-1 (consisting of push-in terminals 24 [GND-1], 25, and 26) and/or RS485-2 (consisting of push-in terminals 29, 30, and 31 [GND-2]).

NOTE: GND-2 is internally connected with 24V-0 (terminal 1)

BACnet MS/TP Bus Considerations

RS485-1 (isolated)

- Max. BACnet MS/TP bus length: 1200 meters (9.6 78.8 kbps) or 800 meters (115.2 kbps) (see also section "RS485 Standard" on pg. 10).
- Use only shielded, twisted-pair cable and daisy-chain topology.
- Must conform to EIA-RS485 cabling guidelines (see section "EIA 485 Cable Specifications" on pg. 40).

• RS485-2 (non-isolated)

- Max. BACnet MS/TP bus length: 1200 meters (9.6 78.8 kbps) or 800 meters (115.2 kbps) (see also section "RS485 Standard" on pg. 10).
- Use only shielded, twisted-pair cable and daisy-chain topology.
- Ground noise should not exceed the EIA-485 common mode voltage limit.
- Must conform to EIA-RS485 cabling guidelines.
- Should not extend beyond a single building.

Connecting Contr. via RS485-1 to BACnet MS/TP Bus

With regards to Fig. 46 through Fig. 48, please note the following:

NOTE: Always power each EAGLEHAWK NX controller and the connected BACnet MS/TP modules via separate transformers.

NOTE: For "L," see section "RS485 Standard" on pg. 10.

NOTE: If any of the devices are electrically isolated, it is recommended that those devices be connected to signal ground. See section "RS485 Standard" on pg. 10.

Example 1: Single EAGLEHAWK NX Controller and Connected BACnet Modules (with inserted termination resistor)

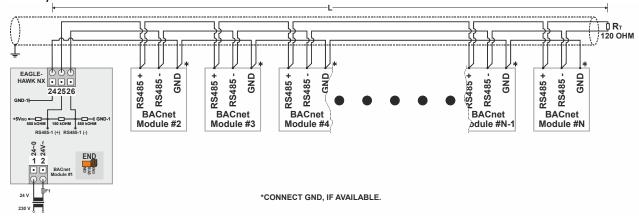


Fig. 46. Connection of a single EAGLEHAWK NX controller via its RS485-1 interface to a BACnet MS/TP Bus

The termination resistor must be inserted directly into the terminals of the last BACnet MS/TP module.

Example 2: Multiple EAGLEHAWK NX Controllers and Connected BACnet Modules

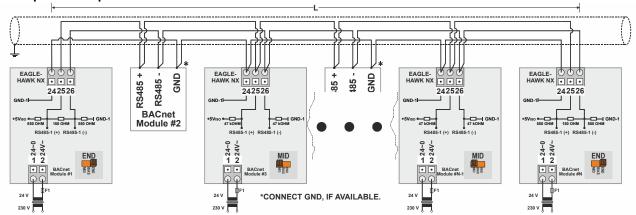


Fig. 47. Connection of multiple EAGLEHAWK NX controllers via their RS485-1 interfaces to a BACnet MS/TP Bus

Example 3: Multiple EAGLEHAWK NX Controllers and Connected BACnet Modules (with inserted termination resistor)

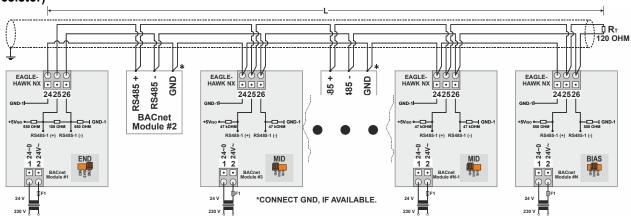


Fig. 48. Connection of multiple EAGLEHAWK NX controllers via their RS485-1 interfaces to a BACnet MS/TP Bus

The termination resistor must be inserted directly into the terminals of the last BACnet MS/TP module (in this example, that is the rightmost EAGLEHAWK NX, the 3-position slide switch of which has been set to "BIAS.")

Connecting Contr. via RS485-2 to BACnet MS/TP Bus

With regards to Fig. 49 and Fig. 50, please note the following:

NOTE: Always power each EAGLEHAWK NX controller and the connected BACnet MS/TP modules via separate transformers.

transionners.

NOTE: For "L," see section "RS485 Standard" on pg. 10.

NOTE: If any of the devices are electrically isolated, it is recommended that those devices be connected to signal ground. See

section "RS485 Standard" on pg. 10.

NOTE: Between devices equipped with non-isolated RS485 bus interfaces, potential differences of max. ±7 V are allowed.

Further, this bus should not extend beyond a single building.

Example 1: Single EAGLEHAWK NX Controller and Connected BACnet Modules (with inserted termination resistor)

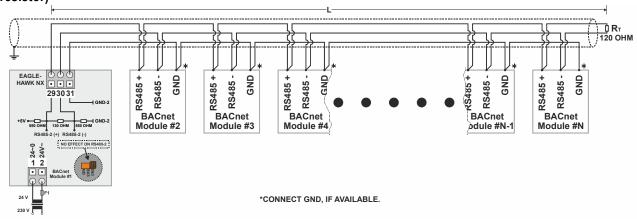


Fig. 49. Connection of a single EAGLEHAWK NX controller via its RS485-2 interface to a BACnet MS/TP Bus

The termination resistor must be inserted directly into the terminals of the last BACnet MS/TP module.

Example 2: Multiple EAGLEHAWK NX Controllers and Connected BACnet Modules

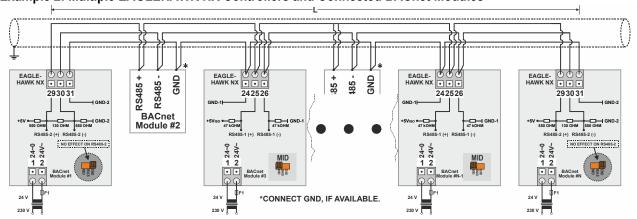


Fig. 50. Connection of multiple EAGLEHAWK NX controllers via their RS485-2 interfaces to a BACnet MS/TP Bus

MODBUS CONNECTION

The EAGLEHAWK NX controller supports both Modbus RTU master and Modbus RTU slave functionality.

Modbus slaves can be connected to either or both of the two onboard RS485 interfaces: RS485-1 (consisting of push-in terminals 24 [GND-1], 25, and 26) or RS485-2 (consisting of push-in terminals 29, 30, 31 [GND-2]).

NOTE: GND-2 is internally connected with 24V-0 (terminal 1)

Modbus Considerations

RS485-1 (isolated)

- Max. Modbus length: 1200 meters (9.6 78.8 kbps) or 800 meters (115.2 kbps) (see also section "RS485 Standard" on pg. 10).
- Use only shielded, twisted-pair cable and daisy-chain topology.
- Must conform to EIA-RS485 cabling guidelines (see section "EIA 485 Cable Specifications" on pg. 40).

RS485-2 (non-isolated)

- Max. Modbus length: 1200 meters (9.6 78.8 kbps) or 800 meters (115.2 kbps) (see also section "RS485 Standard" on pg. 10).
- Use only shielded, twisted-pair cable and daisy-chain topology.
- Ground noise should not exceed the EIA-485 common mode voltage limit.
- Must conform to EIA-RS485 cabling guidelines (see section "EIA 485 Cable Specifications" on pg. 40).
- Should not extend beyond a single building.
- Max. no of Modbus devices per EAGLEHAWK NX RS485 interface: 32 (including the EAGLEHAWK NX, itself, which is counted twice)

Connecting Contr. via RS485-1 to Modbus

With regards to Fig. 51, please note the following:

NOTE: Always power each EAGLEHAWK NX controller and the connected Modbus slaves via separate transformers.

NOTE: For "L," see section "RS485 Standard" on pg. 10.

NOTE: If any of the devices are electrically isolated, it is recommended that those devices be connected to signal ground. See section "RS485 Standard" on pg. 10.

Example: EAGLEHAWK NX Modbus Master Controller and Connected Modbus Slaves (with inserted termination resistor)

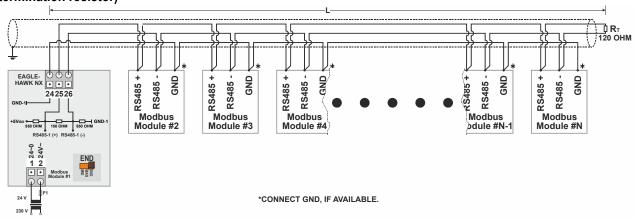


Fig. 51. Connection of an EAGLEHAWK NX Modbus master controller via its RS485-1 interface to a Modbus with slaves. The termination resistor must be inserted directly into the terminals of the last Modbus slave.

NOTE: In this example, any or all of the Modbus RTU slaves depicted here can be EAGLEHAWK NX Modbus RTU slaves. In such cases, an EAGLEHAWK NX Modbus RTU slave positioned at the end of the Modbus (as "Modbus Module #N") must have its 3-position slide switches set to "End" (see Fig. 17) (the insertion of the aforementioned termination resistor is then unnecessary) and any EAGLEHAWK NX Modbus RTU slaves positioned elsewhere on the Modbus must have their 3-position slide switch set to "Mid" (see Fig. 15).

Connecting Contr. via RS485-2 to Modbus

With regards to Fig. 52, please note the following:

NOTE: Always power each EAGLEHAWK NX controller and the connected Modbus slaves via separate transformers.

NOTE: For "L," see section "RS485 Standard" on pg. 10.

NOTE: If any of the devices are electrically isolated, it is recommended that those devices be connected to signal ground. See

section "RS485 Standard" on pg. 10.

NOTE: Between devices equipped with non-isolated RS485 bus interfaces, potential differences of max. ±7 V are allowed.

Further, this bus should not extend beyond a single building.

Example: EAGLEHAWK NX Modbus Master Controller and Connected Modbus Slaves (with inserted termination resistor)

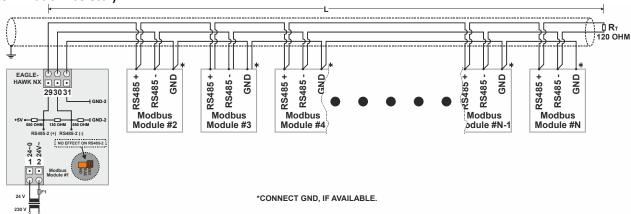


Fig. 52. Connection of an EAGLEHAWK NX Modbus master controller via its RS485-2 interface to a Modbus with slaves

The termination resistor must be inserted directly into the terminals of the last Modbus slave.

NOTE: In this example, a maximum of one of the Modbus RTU slaves can be an EAGLEHAWK NX Modbus RTU slave – which must then be positioned at the end of the Modbus (as "Modbus Module #N"); the insertion of the aforementioned termination resistor is then unnecessary.

M-BUS CONNECTION

The EAGLEHAWK NX controller supports M-Bus Master functionality via its onboard RS232 / RJ45 socket. It uses standard PW3/PW20/PW60 converters to connect to the M-Bus devices.

M-Bus Considerations

Max. no. of M-Bus devices per EAGLEHAWK NX: 60.

Bus Length

- Max. M-Bus length: 350 meters from PW3 / PW20 / PW60, at communication rates of 9.6 kbps or slower with shielded, twisted pair cable: J-Y-(St)-Y 4 x 2 x 0.8.
- The M-Bus can be extended to 1,000 meters, depending upon the communication rate, and provided that the following electrical limitations are observed:
 - Bus voltage must at no point fall below 12 VDC
 - Maximum cable capacitance of 180 nF

For bus length extension, M-Bus repeaters can be used, but have not been tested by Honeywell. Hence, it is the responsibility of the installing / commissioning personnel to ensure proper functioning.

Wiring Topology

M-Bus meters are connected to the bus cable in parallel.

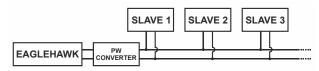


Fig. 53. Allowed M-Bus wiring topology

Cabling EAGLEHAWK NX to PW3/PW20/PW60

- Use the XW586 cable between the RS232 / RJ45 socket of the EAGLEHAWK NX and the PW adapters.
- The XW586 cable has a length of 1.8 m, and the pin-out listed in Table 32.
- In case a third-party cable is used instead of the XW586 cable, the third-party cable must have a max. length of 15 meters and a max. cable capacitance of 2,500 pF.

Table 31. EAGLEHAWK NX RS232 / RJ45 socket specifications

RJ45 plug, pin no.	RS232 function
1	
2	RxD
3	TxD
4	
5	GND
6	
7	
8	

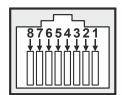


Fig. 54. EAGLEHAWK NX RS232 / RJ45 socket

Table 32. RS232-to-PW cable specifications

RJ45 plug, pin no.	RS232 function	9-Pin sub-D connector pin no.
1	DCD	1
2	RxD	2
3	TxD	3
4	DTR	4
5	GND	5
6	DSR	6
7	RTS	7
8	CTS	8
	Not used	9

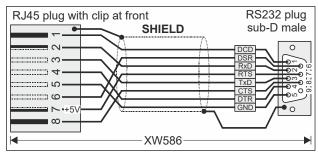


Fig. 55. XW586 power / communication cable details

Cabling PW3/PW20/PW60 to M-Bus

- Use shielded, twisted pair cable J-Y-(St)-Y 4 x 2 x 0.8.
- Shielding is especially recommended when the M-Bus cable is installed in areas with expected or actual electromagnetic noise. Avoiding such areas is to be preferred.
- Connect the shield to a noise-free earth ground only once per M-Bus connection.
- Power the EAGLEHAWK NX controller and the PW M-Bus Adapter with separate transformers – see WARNING below.

NOTE: If, alternatively, only a single transformer is available, when connecting a laptop, PC, web browser, CL-Touch, or 3rd-party touch panel to the USB 2.0 Device Interface on the front of the EAGLEHAWK NX controller, use an optical isolator for the USB connection or substitute an M-Bus Mikro-Master USB (Relay GmbH, D-33106 Paderborn) for the PW M-Bus Adapter.

M-Bus Connection Procedure

 Install the PW M-Bus Adapter on DIN rail. Insert a screwdriver into the slot in the DIN rail clamp on the underside of the PW and pry downward to loosen clamp until the unit snaps onto the rail.

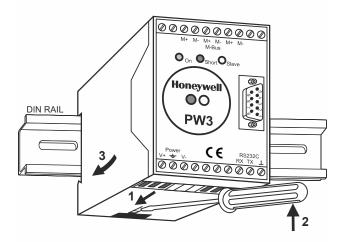


Fig. 56. Mounting of PW (PW3 shown here)

Connect the M-Bus devices to the PW M-Bus Adapter. All M+ and M- terminals are connected in parallel in the PW M-Bus Adapter.

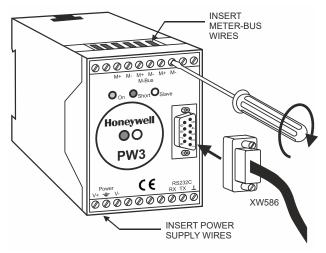


Fig. 57. PW M-Bus adapter connections

Connect the PW M-Bus Adapter to the RS232 / RJ45 socket of the EAGLEHAWK NX using the XW586 cable.

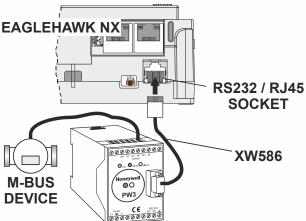


Fig. 58. Connecting the EAGLEHAWK NX to the PW M-Bus adapter

4. Connect 24 V power to the M-Bus Adapter.

⚠ WARNING

Risk of electric shock or equipment damage!

▶ Due to the risk of short-circuiting (see Fig. 24), it is strongly recommended that the EAGLEHAWK NX controller be supplied with power from a dedicated transformer. However, if the EAGLEHAWK NX controller is to be supplied by the same transformer powering other controllers or devices (e.g., the PW M-Bus Adapter), care must be taken to ensure that correct polarity is observed.

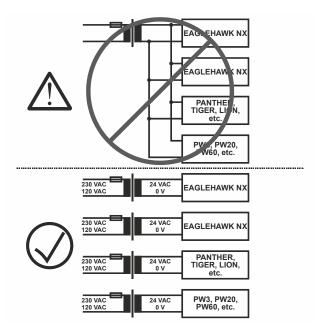


Fig. 59. Connecting power to the PW M-Bus adapter

CONTROLLER PERFORMANCE

The controller performance has been tested in two test scenarios.

NOTE:

These are example scenarios. It is therefore, of course, possible for you to use any other mix of Panel Bus points and BACnet MS/TP points as long as the maximum number of hardware I/O points (see section "Panel Bus Considerations" on pg. 35) is observed.

Table 33. Performance test 1 (simple statement for the COV updates, no HVAC application)

	no. of modules	no. of hardware I/O points	points in PX pages	freq. of value changes	histories enabled	CPU usage	test result
Panel Bus (via RS485-1)	46 ^{(A}	491	491 ^{(B}	2 sec (poll rate)		30% (occasionally:	OK for non-critical
BACnet MS/TP (via RS485-2)	13	559	559 ^{(D}	2 sec (COV)	500	50%)	applications ^(C)

⁽A 9x CLIOP821A, 9x CLIOPR822A, 9x CLIOP823A, 9x CLIOPR824, 5x CLIOPR825, 5x CLIOP830A

Table 34. Performance test 2

	COV frequency	max. no. of COV updates per min. across RS485-1 and RS485-2 together	CPU usage	test result
BACnet MS/TP at 38,500 bps	4 sec	4,000	2535% (occasionally: 60%)	ОК

⁽B Four (4) PX pages: AI, AO, BI, and BO points each in a dedicated PX page per point type

^{(C} About 0.5% of the BACnet MS/TP point updates are occasionally delayed.

⁽D One (1) PX page with all points

TROUBLESHOOTING

EAGLEHAWK NX Controller Troubleshooting

The following LEDs of the EAGLEHAWK NX controller can be used for troubleshooting purposes:

- Power LED (green)
- · Status LED (red)
- L1 and L2 LEDs (yellow)
- Tx (sending data on RS485-1) and Rx (receiving data on RS485-1) LEDs

Power LED (green) of EAGLEHAWK NX

Table 35. EAGLEHAWK NX controller power LED

case	power LED	meaning	remedy
1	ON	Normal operation.	No action necessary.
2	OFF	Power supply not OK.	► Check power supply voltage.
			► Check wiring.
			▶ If problem persists, replace hardware.

Status LED (red) of EAGLEHAWK NX

Table 36. EAGLEHAWK NX controller status LED

case	status LED	meaning	remedy
	<u></u>		
1	OFF after power-up	Normal operation.	No action necessary.
2	ON con- tinuously after	 Indicates an active alarm; is controlled by Niagara Alarm System; is configurable. 	➤ Try powering down and then powering up the EAGLEHAWK NX controller.
	power-up		► If problem persists, replace hardware.

L1 LED

Table 37. EAGLEHAWK NX controller bus L1 LED

case	bus LED	meaning	remedy
1	ON con- tinuously after power-up	Normal operation; Daemon starting.	No action necessary.
2	Flashes constantly	Station starting; if L2 is also flashing, then the station has started.	No action necessary.
3	OFF	Severe software problems.	► Contact TAC.

L2 LED

Table 38. EAGLEHAWK NX controller bus L2 LED

case	L2	meaning	remedy
1	ON con- tinuously after power-up	Platform has started / is reachable.	No action necessary.
2	OFF	Station is not running.	► Start station (enable auto start).► Contact TAC.
3	Flashing	Station has started.	No action necessary.

Tx and Rx LEDs

Table 39. EAGLEHAWK NX controller bus LEDs Tx and Rx

case	bus LEDs	meaning	remedy
	Tx Rx		
1	Both Tx and Rx	Normal operation; RS485-1 is functioning	No action necessary.
	are flashing	properly.	► In case of communication problems, check settings (communication rate, parity, etc.).
2	Both Tx and Rx are OFF	No communication on RS485-1.	► Switch ON communication on RS485-1. L1 should then flash. Further handling like case 4 (below).
3	Rx is flashing and Tx is OFF	Communication on RS485-1 has been switched OFF, but the EAGLEHAWK NX is receiving data from other controllers.	➤ Switch ON communication on RS485-1. If this proves unsuccessful, the hardware may be defective.
4	Tx is flashing and Rx is OFF	The EAGLEHAWK NX controller is attempting to establish communication on RS485-1, but there is no answer.	► The communication rate (kbps) on RS485-1 has not been correctly set; other controllers on the bus may have been incorrectly assigned the same device number; wiring problem or hardware defect.

Panel Bus I/O Module Troubleshooting

Please refer to CentraLine I/O Modules - Installation & Commissioning Instructions (EN1Z-0973GE51) for more information about Panel Bus I/O module troubleshooting.

APPENDIX 1: EARTH GROUNDING EAGLEHAWK NX Systems and SELV

In order to avoid distribution of noise or earth ground potential differences over networks or other connections, the EAGLEHAWK NX controller is designed to be in compliance with SELV (Safety Extra-Low Voltage).

Furthermore, SELV offers the greatest possible safety against electrical impact.

To support SELV, all Honeywell external (CRT series) or internal transformers comply with standard EN60742. Earth grounding is therefore not recommended.

EAGLEHAWK NX Systems and Standard EN60204-1

However, if compliance with EN60204-1 is required, note the following:

General Information about EN60204-1

EN60204-1 defines electrical safety for a complete application / machine including controllers, sensors, actuators and any connected/controlled electrical device.

EN60204-1 requires controllers to be powered by PELV (Protective Extra-Low Voltage) and earth grounding of the secondary side of the used transformers or earth grounding of the system ground.

Earth grounding is prescribed to prevent unexpected start-up of connected rotating/moving machines due to an insulation fault and double earth grounding somewhere in the plant. In order to fulfill PELV (if earth grounding is prohibited), the use of an earth leakage monitor is also possible.

When is EN60204-1 Applicable to EAGLEHAWK NX Systems?

- · Safety against electrical impact
 - EN60204-1 is not mandatory; this is because electrical safety is provided by the use of SELV and transformers according to standard EN60742.
- Safety against unexpected start-up of rotating/moving machines
 - If the application/plant does not contain machines that can be harmful to the operator due to an unexpected start-up, the standard EN60204-1 is not applicable.

If such machines are encountered, then EN60204-1 must be followed. Grounding is required.

Earth Grounding of EN60204-1 Applicable Systems

NOTE: We strongly recommend that each CPU be supplied with electricity from its own dedicated transformer.

- If system protective earth grounding is planned, use a cable as short as possible for grounding: min. 1.5 mm² (16 AWG).
- ▶ For connection details, refer to the following examples.

Example 1

The following explains how to connect and earth multiple CPUs (e.g., multiple EAGLEHAWK NX controllers, PANTHERs, TIGERs, LIONs, etc. or any combination thereof) earth-grounded as per EN60204-1.

monitoring device must be used instead of earth

NOTE: Use a noise-free earth ground inside the cabinet.

NOTE: If a field device that prohibits earth grounding is connected to the system ground, an isolation

grounding.

 Connect earth ground to the respective terminal of the CPU, see Fig. 60.

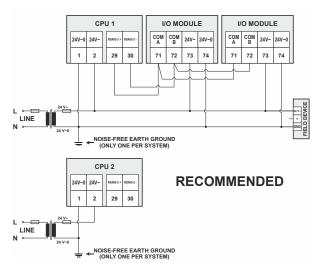


Fig. 60. Connecting and earthing multiple CPUs (RECOMMENDED USE OF SEPARATE TRANSFORMERS)

Example 2

When connecting multiple CPUs to a single transformer, it is imperative that the polarity of the power supply terminals of the CPUs and the polarity of the transformer always correspond (namely: 24V-0 of the transformer must always be connected to 24V-0 of the CPU, and 24V~ of the transformer must always be connected with 24V~ of the CPU).

Depending upon the individual CPU, the numbering of the corresponding two terminals may possibly deviate from the norm (which is usually "terminal 1 = 24V-0" and "terminal 2 = 24V-"). In the following example, CPU 3 has a deviating numbering and must be connected accordingly.

NOTE: When using a single transformer for several CPUs, each CPU ground must be wired separately to the star-point.

NOTE: If the field device transformer is physically far away from the CPUs, earth grounding must still be

performed for the controller.

NOTE: Use one star-point to split power for multiple CPUs

and field devices.

Connect earth ground to the proper terminal of the CPU, see Fig. 61.

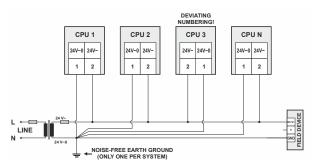


Fig. 61. Connecting and earthing multiple CPUs

APPENDIX 2

Sensor Input Accuracy

The internal sensor inputs of the EAGLEHAWK NX controller support both NTC10k Ω and NTC20k Ω sensors (see also section "Universal Inputs" on page 26). The following table lists the typical minimum accuracies of the hardware and software for temperature sensors.

Table 40. Accuracies of internal NTC20kΩ sensor inputs of the EAGLEHAWK NX

range	measurement error (excl. sensor characteristics)		
	NTC10kΩ sensors ⁽¹	NTC20kΩ sensors	
-5020 °C (-584 °F)	≤ 5.0 K	≤ 5.0 K	
-20 0 °C (-4 +32 °F)	≤ 1.0 K	≤ 1.0 K	
0 30 °C (32 86 °F)	≤ 0.5 K	≤ 0.3 K	
30 70 °C (86 158 °F)	≤ 0.5 K	≤ 0.5 K	
70 100 °C (158 212 °F)	≤ 1.0 K	≤ 1.0 K	
100 130 °C (212 266 °F)		≤ 3.0 K	
130 150 °C (266 302 °F)		≤ 5.5 K	
150 400 °C (302 752 °F)			
⁽¹ NTC10kΩ specified for -30 +100 °C, only.			

NOTE: This is the accuracy of the internal sensor input (hardware + software [linearization]), only. This table does not include the characteristics of the sensors, themselves (see section "Sensor Characteristics" below). If a different sensor or sensor accuracy is required, one may instead use the inputs of, e.g., a connected Panel I/O module.

Recognition of Sensor Failure of Sensor Inputs

The thresholds at which sensor failures – i.e., sensor breaks (SB) and short-circuits (SC) – are recognized depends upon the given sensor type. In the event of a recognized sensor failure, the sensor inputs assume the safety values configured in COACH NX. Table 41 lists the measurement ranges and the corresponding thresholds for the recognition of sensor failure for the various different sensor types:

Table 41. Thresholds for short-circuit (SC) and sensor-break (SB) recognition

I/O configuration	measurement range	recognition thresholds
210 V	210 V / 420 mA (without pull-up)	SC: < 1.5 V / 3 mA; SB: no recognition
ΝΤC10kΩ	-30 +100 °C	SC: < 20 Ω; SB: < -70 °C
ΝΤC20kΩ	-50 +150 °C	SC: < 20 Ω; SB: < -70 °C

NOTE: In the case of temperatures lying *outside* the aforementioned ranges, the lowest/highest value *within* the range, instead, will be communicated. Thus, a temperature of -51 °C will be communicated as "-50 °C."

Sensor Characteristics

The characteristics (resistance in relation to temperature) of the sensors and the resultant voltage are listed on the following pages. The stated values do not include failures due to: sensor failures; wiring resistance or wiring failures; misreadings due to a meter connected to measure resistance or voltage at the input.

NTC 20 k Ω (same voltages for inputs of Panel Bus I/O Modules and onboard inputs of EAGLEHAWK NX)

NTC 20	kΩ (sam	e voltag
Temp.	Resistance	Terminal
	[kΩ] 1659	voltage [V] 8.78
-49.0	1541	8.77
-48.0	1432	8.76
-47.0	1331	8.75
-46.0	1239	8.74
-45.0	1153	8.72
-44.0	1073	8.71
-43.0	1000	8.70
-42.0	932	8.69
-41.0	869	8.67
-40.0	811	8.66
-39.0	757	8.64
-38.0	706	8.62
-37.0	660	8.60
-36.0	617	8.58
-35.0	577	8.56
-34.0	539	8.54
-33.0	505	8.52
-32.0	473	8.49
-31.0	443	8.47
-30.0	415	8.44
-29.0	389	8.41
-28.0	364	8.38
-27.0	342	8.35
-26.0	321	8.32
-25.0	301	8.28
-24.0	283	8.25
-23.0	266	8.21
-22.0	250	8.17
-21.0	235	8.13
-20.0	221	8.08
-19.0	208	8.04
-18.0	196	7.99
-17.0	184	7.94
-16.0	174	7.89
-15.0	164	7.83
-14.0	154	7.78
-13.0	146	7.72
-12.0	137	7.66
-11.0	130	7.60
-10.0	122	7.53
-9.0	116	7.46
-8.0	109	7.39
-7.0	103	7.32
-6.0	97.6	7.25
-5.0	92.3	7.17
-4.0	87.3	7.09
-3.0	82.6	7.01
-2.0	78.2	6.93
-1.0	74.1	6.85
0.0	70.2	6.76
1.0	66.5	6.67
2.0	63.0	6.58
3.0	59.8	6.49
4.0	56.7	6.40
5.0	53.8	6.30
5.0	55.6	0.30

Temp.	Resistance	Terminal
[°C]	[kΩ]	voltage [V]
6.0	51.1	6.20
7.0	48.5	6.10
8.0	46.0	6.00
9.0	43.7	5.90
10.0	41.6	5.80
11.0	39.5	5.70
12.0	37.6	5.59
13.0	35.7	5.49
14.0	34.0	5.38
15.0	32.3	5.28
16.0	30.8	5.17
17.0	29.3	5.07
18.0	27.9	4.96
		4.85
19.0	26.6	
20.0	25.3	4.75
21.0	24.2	4.64
22.0	23.0	4.53
23.0	22.0	4.43
24.0	21.0	4.32
25.0	20.0	4.22
26.0	19.1	4.12
27.0	18.2	4.01
28.0	17.4	3.91
29.0	16.6	3.81
30.0	15.9	3.71
31.0	15.2	3.62
32.0	14.5	3.52
33.0	13.9	3.43
34.0	13.3	3.33
35.0	12.7	3.24
36.0	12.1	3.15
37.0	11.6	3.06
38.0	11.1	2.97
39.0	10.7	2.89
40.0	10.2	2.81
41.0	9.78	2.72
42.0	9.37	2.64
43.0	8.98	2.57
44.0	8.61	2.49
45.0	8.26	2.42
46.0	7.92	2.34
47.0	7.60	2.27
48.0	7.29	2.20
49.0	7.00	2.14
50.0	6.72	2.07
51.0	6.45	2.01
52.0	6.19	1.94
53.0	5.95	1.88
54.0	5.72	1.82
55.0	5.49	1.77
56.0	5.28	1.71
57.0	5.08	1.66
58.0	4.88	1.61
59.0	4.69	1.56
60.0	4.52	1.51

61.0

4.35

odules a		ard inpu
Temp. [°C]	Resistance [kΩ]	Terminal voltage [V]
62.0	4.18	1.41
63.0	4.03	1.37
64.0	3.88	1.32
65.0	3.73	1.28
66.0	3.59	1.24
67.0	3.46	1.20
68.0	3.34	1.16
69.0	3.21	1.13
70.0	3.10	1.09
71.0	2.99	1.06
72.0	2.88	1.02
73.0	2.78	0.991
74.0	2.68	0.960
75.0	2.58	0.929
76.0	2.49	0.900
77.0	2.41	0.872
78.0	2.32	0.844
79.0	2.24	0.818
80.0	2.17	0.792
81.0	2.09	0.767
82.0	2.02	0.744
83.0	1.95	0.720
84.0	1.89	0.698
85.0	1.82	0.676
86.0	1.76	0.655
87.0	1.70	0.635
88.0	1.65	0.616
89.0	1.59	0.597
90.0	1.54	0.578
91.0	1.49	0.561
92.0	1.44	0.544
93.0	1.40	0.527
94.0	1.35	0.511
95.0	1.31	0.496
96.0	1.27	0.481
97.0	1.23	0.466
98.0	1.19	0.452
99.0	1.15	0.439
100.0	1.11	0.425
101.0	1.08	0.413
102.0	1.05	0.401
103.0	1.01	0.389
104.0	0.98	0.378
105.0	0.95	0.367
106.0	0.92	0.356
107.0	0.90	0.346
108.0	0.87	0.336
109.0	0.84	0.326
110.0	0.82	0.317
111.0	0.79	0.308
112.0	0.77	0.299
113.0	0.75	0.290
114.0	0.73	0.282
115.0	0.70	0.274
116.0	0.68	0.266
117.0	0.66	0.259

Temp. [rc] Resistance [κΩ] Terminal voltage [V] 118.0 0.64 0.252 119.0 0.63 0.245 120.0 0.61 0.238 121.0 0.59 0.231 122.0 0.57 0.225 123.0 0.56 0.219 124.0 0.54 0.213 125.0 0.53 0.207 126.0 0.51 0.201 127.0 0.50 0.196 128.0 0.49 0.191 129.0 0.47 0.186 130.0 0.46 0.181 131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142	f EAGLE	:HAWK	NX)
119.0 0.63 0.245 120.0 0.61 0.238 121.0 0.59 0.231 122.0 0.57 0.225 123.0 0.56 0.219 124.0 0.54 0.213 125.0 0.53 0.207 126.0 0.51 0.201 127.0 0.50 0.196 128.0 0.49 0.191 129.0 0.47 0.186 130.0 0.46 0.181 131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 <td< th=""><th></th><th></th><th></th></td<>			
120.0 0.61 0.238 121.0 0.59 0.231 122.0 0.57 0.225 123.0 0.56 0.219 124.0 0.54 0.213 125.0 0.53 0.207 126.0 0.51 0.201 127.0 0.50 0.196 128.0 0.49 0.191 129.0 0.47 0.186 130.0 0.46 0.181 131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 <td< td=""><td>118.0</td><td>0.64</td><td>0.252</td></td<>	118.0	0.64	0.252
121.0 0.59 0.231 122.0 0.57 0.225 123.0 0.56 0.219 124.0 0.54 0.213 125.0 0.53 0.207 126.0 0.51 0.201 127.0 0.50 0.196 128.0 0.49 0.191 129.0 0.47 0.186 130.0 0.46 0.181 131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 <td< td=""><td>119.0</td><td>0.63</td><td>0.245</td></td<>	119.0	0.63	0.245
122.0 0.57 0.225 123.0 0.56 0.219 124.0 0.54 0.213 125.0 0.53 0.207 126.0 0.51 0.201 127.0 0.50 0.196 128.0 0.49 0.191 129.0 0.47 0.186 130.0 0.46 0.181 131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.128 145.0 <td< td=""><td>120.0</td><td>0.61</td><td>0.238</td></td<>	120.0	0.61	0.238
123.0 0.56 0.219 124.0 0.54 0.213 125.0 0.53 0.207 126.0 0.51 0.201 127.0 0.50 0.196 128.0 0.49 0.191 129.0 0.47 0.186 130.0 0.46 0.181 131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.128 145.0 0.31 0.122 146.0 <td< td=""><td>121.0</td><td>0.59</td><td>0.231</td></td<>	121.0	0.59	0.231
124.0 0.54 0.213 125.0 0.53 0.207 126.0 0.51 0.201 127.0 0.50 0.196 128.0 0.49 0.191 129.0 0.47 0.186 130.0 0.46 0.181 131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.128 145.0 0.30 0.119 147.0 0.29 0.116 148.0 <td< td=""><td>122.0</td><td>0.57</td><td>0.225</td></td<>	122.0	0.57	0.225
125.0 0.53 0.207 126.0 0.51 0.201 127.0 0.50 0.196 128.0 0.49 0.191 129.0 0.47 0.186 130.0 0.46 0.181 131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 <td< td=""><td>123.0</td><td>0.56</td><td>0.219</td></td<>	123.0	0.56	0.219
126.0 0.51 0.201 127.0 0.50 0.196 128.0 0.49 0.191 129.0 0.47 0.186 130.0 0.46 0.181 131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 <td< td=""><td>124.0</td><td>0.54</td><td>0.213</td></td<>	124.0	0.54	0.213
127.0 0.50 0.196 128.0 0.49 0.191 129.0 0.47 0.186 130.0 0.46 0.181 131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	125.0	0.53	0.207
128.0 0.49 0.191 129.0 0.47 0.186 130.0 0.46 0.181 131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	126.0	0.51	0.201
129.0 0.47 0.186 130.0 0.46 0.181 131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	127.0	0.50	0.196
130.0 0.46 0.181 131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	128.0	0.49	0.191
131.0 0.45 0.176 132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	129.0	0.47	0.186
132.0 0.43 0.171 133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	130.0	0.46	0.181
133.0 0.42 0.167 134.0 0.41 0.162 135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	131.0	0.45	0.176
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135.0 0.40 0.158 136.0 0.39 0.154 137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	133.0	0.42	0.167
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137.0 0.38 0.150 138.0 0.37 0.146 139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	135.0	0.40	0.158
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139.0 0.36 0.142 140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	137.0	0.38	0.150
140.0 0.35 0.139 141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	138.0	0.37	0.146
141.0 0.34 0.135 142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	139.0	0.36	0.142
142.0 0.33 0.132 143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	140.0	0.35	0.139
143.0 0.32 0.128 144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	141.0	0.34	0.135
144.0 0.32 0.125 145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	142.0	0.33	0.132
145.0 0.31 0.122 146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	143.0	0.32	0.128
146.0 0.30 0.119 147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	144.0	0.32	0.125
147.0 0.29 0.116 148.0 0.29 0.113 149.0 0.28 0.110	145.0	0.31	0.122
148.0 0.29 0.113 149.0 0.28 0.110	146.0	0.30	0.119
149.0 0.28 0.110	147.0	0.29	0.116
	148.0	0.29	0.113
150.0 0.27 0.107	149.0	0.28	0.110
	150.0	0.27	0.107

1.46

NTC10kΩ (same voltages for inputs of Panel Bus I/O Modules and onboard inputs of EAGLEHAWK NX)

NTC10I		voltages
Temp. [°C]	Resistance [kΩ]	Terminal voltage [V]
-30	177	7.904
-29	166.35	7.848
-28	156.413	7.790
-27	147.136	7.730
-26	138.47	7.666
-25	130.372	7.601
-24	122.8	7.534
-23	115.718	7.464
-22	109.089	7.392
-21	102.883	7.318
-20	97.073	7.241
-19	91.597	7.161
-18	86.471	7.080
-17	81.667	6.996
-16	77.161	6.910
-15	72.932	6.821
-14	68.962	6.731
-13	65.231	6.639
-12	61.723	6.545
-11	58.424	6.448
-10	55.321	6.351
-9	52.399	6.251
-8	49.648	6.150
-7	47.058	6.047
-6	44.617	5.943
-5	42.317	5.838
-4	40.15	5.732
-3	38.106	5.624
-2	36.18	5.516
-1	34.363	5.408
0	32.65	5.299
1	31.027	5.189
2	29.494	5.079
3	28.047	4.969
4	26.68	4.859
5	25.388	4.750
6	24.166	4.641
7	23.01	4.532
8	21.916	4.423
9	20.88	4.316
10	19.898	4.209
11	18.968	4.103
12	18.087	3.998
-4 -3 -2 -1 0 1 2 3 4 5 6 7 8 9 10 11	40.15 38.106 36.18 34.363 32.65 31.027 29.494 28.047 26.68 25.388 24.166 23.01 21.916 20.88 19.898 18.968	5.732 5.624 5.516 5.408 5.299 5.189 5.079 4.969 4.859 4.750 4.641 4.532 4.423 4.316 4.209 4.103

	of Pane	
Temp. [°C]	Resistance [kΩ]	Terminal voltage [V]
13	17.252	3.894
14	16.46	3.792
15	15.708	3.690
16	14.995	3.591
17	14.319	3.492
18	13.678	3.396
19	13.068	3.300
20	12.49	3.207
21	11.94	3.115
22	11.418	3.025
23	10.921	2.937
24	10.449	2.850
25	10	2.767
26	9.572	2.684
27	9.165	2.603
28	8.777	2.524
29	8.408	2.447
30	8.057	2.372
31	7.722	2.299
32	7.402	2.228
33	7.098	2.159
34	6.808	2.091
35	6.531	2.025
36	6.267	1.962
37	6.015	1.900
38	5.775	1.840
39	5.546	1.781
40	5.327	1.724
41	5.117	1.669
42	4.917	1.616
43	4.726	1.564
44	4.543	1.514
45	4.369	1.465
46	4.202	1.418
47	4.042	1.373
48	3.889	1.329
49	3.743	1.286
50	3.603	1.244
51	3.469	1.204
52	3.34	1.166
53	3.217	1.128
54	3.099	1.092
55	2.986	1.057

<u>quies ai</u>	nd onboa	ira inputs
Temp. [°C]	Resistance [kΩ]	Terminal voltage [V]
56	2.878	1.023
57	2.774	0.990
58	2.675	0.959
59	2.579	0.928
60	2.488	0.898
61	2.4	0.870
62	2.316	0.842
63	2.235	0.815
64	2.158	0.790
65	2.083	0.765
66	2.011	0.740
67	1.943	0.718
68	1.877	0.695
69	1.813	0.673
70	1.752	0.652
71	1.694	0.632
72	1.637	0.612
73	1.583	0.593
74	1.531	0.575
75	1.481	0.557
76	1.433	0.541
77	1.387	0.524
78	1.342	0.508
79	1.299	0.493
80	1.258	0.478
81	1.218	0.464
82	1.179	0.450
83	1.142	0.436
84	1.107	0.423
85	1.072	0.411
86	1.039	0.399
87	1.007	0.387
88	0.976	0.375
89	0.947	0.365
90	0.918	0.354
91	0.89	0.344
92	0.863	0.334
93	0.838	0.324
94	0.813	0.315
95	0.789	0.306
96	0.765	0.297
97	0.743	0.289
98	0.721	0.280

Temp. [°C]	Resistance [kΩ]	Terminal voltage [V]	
99	0.7	0.276	
100	0.68	0.265	

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accuracies. see sensor input accuracies connection, 33 multiple rails, single transformer, 34, 35 via RS485-1, 9 BACnet MS/TP via RS485-1, 6 via RS485-2, 9 BACnet MS/TP via RS485-2, 6 power supply **BACnet IP, 2** failure indication, 51 LED, 8 power supply (field devices) BACnet MS/TP, 2 cable specifications, 41 BACnet MS/TP via RS485-1, 9, 43, 44, 45, 47 via I/O module, 20, 22 BACnet MS/TP via RS485-2, 9 power supply (Panel Bus I/Os) disposal cable specifications, 38 WEEE Directive 2002/96/EC, 2 RS232 / RJ45 socket, 6, 7, 48 Ethernet / RJ45 sockets, 6 safetv details, 8 electrical safety as per EN60204-1, 53 protocol version, 2 general safety information, 2, 20 **External HMI** PELV, 53 power consumption, 3 SELV, 53 extra parts safety values/positions TPU-11-01 removable push-in terminal plugs, 20 safety positions of AOs, 27 TPU-45-01 removable push-in terminal plugs, 20 safety positions of relays, 28 fusing, 20 safety values of sensor inputs, 55 LEDs, 6 sensor characteristics L1, 9, 51 NTC 20 kOhm, 56 L2, 9, 52 sensor input accuracies, 26, 55 power LED, 9, 51 AOs, 27 Rx, 9, 52 Uls, 26 status LED, 9, 51 USB Tx, 9, 52 USB 2.0 Device Interface, 6 M-Bus details, 7 connection, 48 initially accessing EAGLEHAWK NX via Ethernet/IP, Modbus 29 connection, 11, 46 USB 2.0 Host Interface, 6 via RS485-1, 9, 46 details. 7 via RS485-2, 9, 47 **Panel Bus**

Manufactured for and on behalf of the Connected Building Division of Honeywell Products and Solutions Sârl, Z.A. La Pièce 16, 1180 Rolle, Switzerland by its Authorized Representative:

CentraLine Honeywell GmbH Böblinger Strasse 17 71101 Schönaich, Germany Phone +49 (0) 7031 637 01 www.centraline.com

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