

## **TARS-B SERIES**

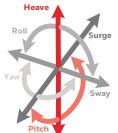
The Transportation Attitude Reference System (TARS) is a packaged sensor array designed to report 6 degrees of freedom IMU data (angular rate and acceleration) and attitude for demanding heavy-duty and off-highway transportation applications.

The TARS Series enhances efficiency and productivity by reporting key data required to aid in system automation and motion monitoring. Its features may also be customized for specific vehicle applications allowing movement data to be filtered for extraneous environment and vehicle movements. (See Tables 1 and 2.)

#### FIGURE 1. TARS IMU

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#### FIGURE 2. SIX DEGREES OF FREEDOM



Translational Movement in Three Perpendicular Axes

Surge: Moving forward/backward Heave: Moving up/down Sway: Moving left/right

#### Rotational Movement about Three Perpendicular Axes

Roll: Tilting side to side
Pitch: Tilting forward and backward
Yaw: Turning left and right

## TABLE 1. SENSOR SPECIFICATIONS

Characteristic	TARS-HCASS (TARS SERIES)	TARS-BAASS (TARS-B SERIES)					
Gyroscope	_						
Range	±245 deg/s	±500 deg/s					
ARW (Angular Random Walk)	0.36 deg/√Hz	0.6 deg/√Hz					
In-run bias stability	7.1 deg/hr	3.8 deg/hr					
Accelerometer							
Range	±8 g	±6 g					
VRW (Velocity Random Walk)	0.09 m/s/√Hz	0.08 m/s/√Hz					
In-run bias stability	50 μg	25 μg					
Inclination (pitch and roll)							
Range (roll/pitch)	±90 deg/±90 deg	±180 deg/±90 deg					
Static error (at room temp)	±0.3 deg	±0.2 deg					

#### **TABLE 2. ORDER GUIDE**

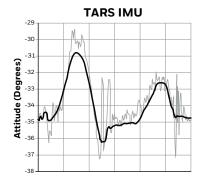
Catalog Listing	Description
TARS-BAASS	TARS-B Series Inertial Measurement Unit, 9 V to 36 V supply voltage, AMPSEAL 16™ Series connector
TARS-SHIELD	Zinc, die-cast protective shield

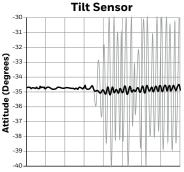
#### **TABLE 3. COMPARISON CHART**

Characteristic	Tilt Sensor	TARS- HCASS	TARS- BAASS	NAV
Gyroscope	no	good	better	best
Accelerometer	good	good	better	best
Attitude	no	good	better	best
Cost	\$	\$\$	\$\$	\$\$\$\$

As shown in Figure 3, the TARS Attitude model fuses gyroscope and accelerometer data to produce high-quality attitude estimates and eliminates the effects of vibration and motion as observed in the tilt sensor.

#### FIGURE 3. TARS IMU VS TILT SENSOR





#### **ENHANCEMENTS**

- Improved gyroscope stability reduces the amount of attitude correction and improves dynamic accuracy when the application is in constant motion. Also, the improved rotation rate range was implemented with minimal change in sampling noise.
- Improved accelerometer accuracy and stability enhances both static attitude accuracy measurements and improves motion tracking.
- Attitude calculation model enhancements include improved attitude correction and special functions such as mounting errors, offset correction and aid in motion monitoring.

#### **FEATURES**

- J1939 compliant
- Configurable and updateable
- Small form-factor, ruggedized PBT thermoplastic housing (IP67 and IP69K)
- Optional shield for impact protection
- Customizable filters to minimize noise
- Customizable Extended Kalman Filter
- 9 V to 36 V, supply, -40°C to 85°C operating temperature

#### **POTENTIAL APPLICATIONS**

Heavy-duty vehicle stability, motion tracking, work monitoring, operator assist and performance optimization.

#### WARRANTY/REMEDY

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DO NOT USE these products as safety or emergency stop devices or in any other application where failure of the product could result in personal injury.

Failure to comply with these instructions could result in death or serious injury.

### **⚠ WARNING** MISUSE OF DOCUMENTATION

- The information presented in this product sheet is for reference only. Do not use this document as a product installation guide.
- Complete installation, operation, and maintenance information is provided in the instructions supplied with each product.

Failure to comply with these instructions could result in death or serious iniury.

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