Technical Note

Entering and Using Command Mode on the Honeywell Humidlcon™ Digital Humidity/Temperature Sensors

1.0 Introduction

Command Mode is used on the Honeywell HumidIcon™ Digital Humidity/Temperature Sensors for reading and writing to the on-chip EEPROM. Command Mode allows the user to configure and optimize sensor performance to match application requirements. User-configurable options include alarm settings, I²C address and customer identification bytes.

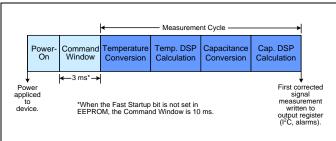
This document describes:

- How to enter Command Mode.
- How to use Command Mode to configure the sensor.
- An example of the required configuration steps.

2.0 Power-On Sequence

Figure 1 shows the Power-On sequence.

Figure 1. Power-On Sequence with a 3 ms Command Window

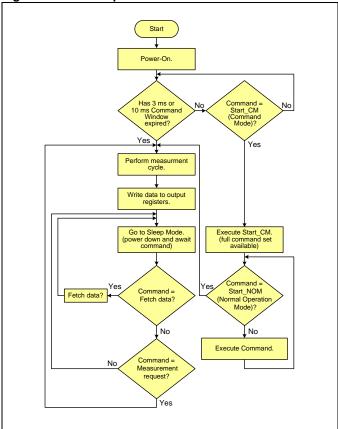


After Power-On, the Command Window is entered. The Command Window can be configured to be either 3 ms or 10 ms in duration (see Section 4.1). If the sensor receives a "Start_CM" command during the Command Window, it enters and remains in Command Mode.

While the sensor is in Command Mode it communicates as an I^2C device regardless of its preconfigured output protocol. The sensor clock pin becomes the I^2C clock pin (SCL) and the sensor data pin becomes the I^2C data pin (SDA).

If, during the Power-On sequence, the Command Window expires without receiving a "Start_CM" command, or if the sensor receives a "Start_NOM" command in Command Mode, the sensor will immediately revert to its pre-configured output protocol (either I²C or SPI), perform one complete measurement cycle and write the data to the output registers before entering into sleep mode (see Figure 2).

Figure 2. General Operation Flow Chart



3.0 Command Mode

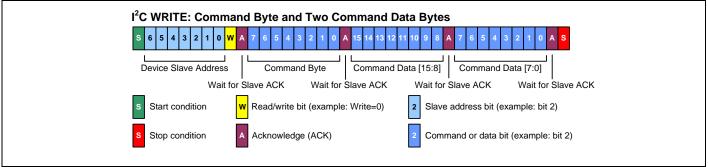
Command Mode is used for configuring the sensor. It is entered by sending a "Start_CM" command during the Command Window (see Section 2.0). In Command Mode a set of commands is available to the user to configure the sensor (see Table 1). All communication in Command Mode is done using I²C protocol regardless of the preconfigured communications protocol of the sensor.

3.1 Command Format

Command Mode commands are supported only for the I^2C protocol. As shown in Figure 3, commands consist of 4-byte packets with the first byte being a 7-bit slave address followed by a Read/Write bit (0 = Write, 1 = Read). The second byte is the command byte, and the last two bytes form a 16-bit data field.

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Figure 3. Command Mode Format



Command Mode Commands 3.2

Table 1 lists all the commands that are available in Command Mode.

Note: Only the commands listed in Table 1 are valid. Other encodings may cause unpredictable behavior. If data is not needed for the command, zeros must be supplied in the data field to complete the 4-byte packet.

Table 1. Command Mode Commands

	Data Bytes	de Commanus	_
Byte	(16-bits,	Description	Response Time
(8-bits, Hex)	Hex)	-	rime
0x00 to 0x1F	0x0000	EEPROM Read of	100 µs
		address 0x00 to 0x1F	
		after this command has	
		been sent and executed, a data fetch must be	
		performed to retrieve the	
		contents of the EEPROM	
		address is specified in the	
		six LSBs of the command	
		byte	
0x40 to 0x5F		Write to EEPROM	12 ms
	(Y=data)	addresses 0x00 to 0x1F	
		the two data bytes sent will	
		be written to the address	
		specified in the six LSBs of	
0x80	0x0000	the command byte Start NOM	42.5 ms
UXOU	000000	Start_INOW	42.5 1115
		ends Command Mode and	
		transitions to Normal	
		Operation Mode	
0xA0	0x0000	Start_CM	100 µs
		starts Command Mode:	
		used to enter Command	
		Mode, is only valid during	
		the Power-On command	
		window (see Section 2.0)	

Note: All time values are typical; for worst case values, add 15%.

3.3 Command response and Data Fetch Format

After a command has been sent and its execution time defined in Table 1 has expired, an I²C Data Fetch is used to read the response.

Figure 4 shows the different Data Fetch formats. After the slave address has been sent, the first byte fetched is the response byte. The response byte consists of two status bits, four diagnostic bits and two response bits.

The upper two bits of the response byte are the status bits. Table 2 describes the conditions that the status bits can report.

The middle four bits of the response byte are command diagnostic bits. Each bit represents a different diagnostic (see Table 3).

The lower two bits of the response byte are the response bits. To determine if a command has finished executing, poll the device until a "Busy" response is no longer received. Table 4 describes the different responses that the sensor can return.

NOTICE

- Regardless of what the response bits are, one or more of the diagnostic bits may be set indicating an error has occurred during the execution of the command.
- Only one command may be executed at a time. After a command is sent, another command must not be sent until the execution time of the first command has expired. Alternatively the response bits can be polled to determine when the command has completed execution.

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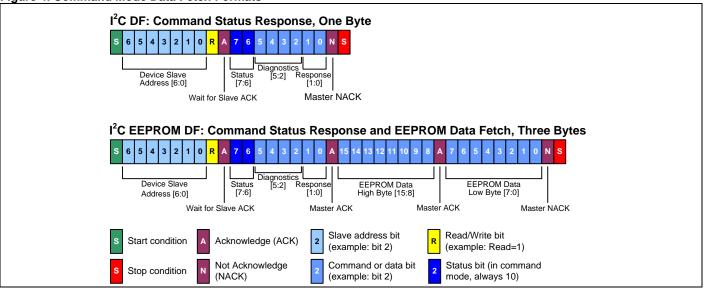


Table 2. Status Bits

Status Bits		Definition	
S1	S0	Definition	
0	0	normal operation, valid data	
0	1	stale data: data that has already been fetched since the last measurement cycle, or data fetched before the first measurement cycle has been completed	
1	0	device in Command Mode	
1	1	not used	

Table 3. Diagnostic Bits

Diagnostic Bits			its	Name	Description
D3	D2	D1	D0	Name	Description
х	х	х	1	corrected EEPROM error	a corrected EEPROM error occurred during the execution of the last command
х	x	1	X	uncorrectable EEPROM error	an uncorrectable EEPROM error occurred during the execution of the last command
х	1	х	x	RAM parity error	a RAM parity error occurred during the execution of the last command
1	х	х	Х	configuration error	an EEPROM or RAM parity error occurred during the initial loading of the configuration registers

Table 4. Response Bits

Response Bits		Definition	Description
R1	R0		•
0	0	busy	the command is still executing
0	1	positive acknowledge	the command executed successfully
1	0	negative acknowledge	the command was not recognized or an EEPROM write was attempted to a locked EEPROM location
1	1	ne	ot used

4.0 **EEPROM**

The EEPROM array contains the configuration bits for the I²C slave address, alarms, Command Window duration and customer identification. The EEPROM is organized as 32 16bit words (see Table 5). The EEPROM is divided into two sections:

- EEPROM locations 0x00 to 0x15 are locked and can no longer be written to.
- EEPROM locations 0x16 to 0x1F are unlocked and may be modified by the customer.

NOTICE

Any modifications to EEPROM locations require a power cycle for the changes to take effect.

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Table 5. EEPROM Memory Map

EEPROM	Name	Description	
Address		•	
0x00 to	reserved	do not change; must be left at	
0x15		factory settings; locked EEPROM locations	
0x16	reserved	do not change ; must be left at factory settings	
0x17	reserved	do not change ; must be left at factory settings	
0x18	Alarm_High_On	high alarm on trip point	
0x19	Alarm_High_Off	high alarm off trip point	
0x1A	Alarm_Low_On	low alarm on trip point	
0x1B	Alarm_Low_Off	low alarm off trip point	
0x1C	Cust_Config	Customer Configuration	
		Register (see Section 4.1)	
0x1D	reserved	do not change ; must be left at factory settings	
0x1E	Cust_ID2	customer ID word: for use by customer	
0x1F	Cust_ID3	customer ID word: for use by customer	

4.1 Customer Configuration Register

The Customer Configuration Register (see table 6) is located at EEPROM location 0x1C. The register is loaded at Power-On.

5.0 Digital Humidity/Temperature Sensor Configuration Example

Command Mode is used to configure Honeywell digital humidity/temperature sensors. A few basic steps and I²C communications are all that is required for a user to optimize the sensor for the application.

Figure 5 shows the steps required to enable a digital humidity sensor in the configuration described below:

- Alarm_High_On = 80% humidity
- Alarm_Low_On = 20% humidity
- Alarm_High_Off = 75% humidity
- Alarm_Low_Off = 25% humidity
- I^2C Address = 0x53
- Command Window = 3 ms
- Alarm_High = Active_High
- Alarm_Low = Active_High
- Alarm_High = Full_Push-Pull Output
- Alarm_Low = Full_Push-Pull Output

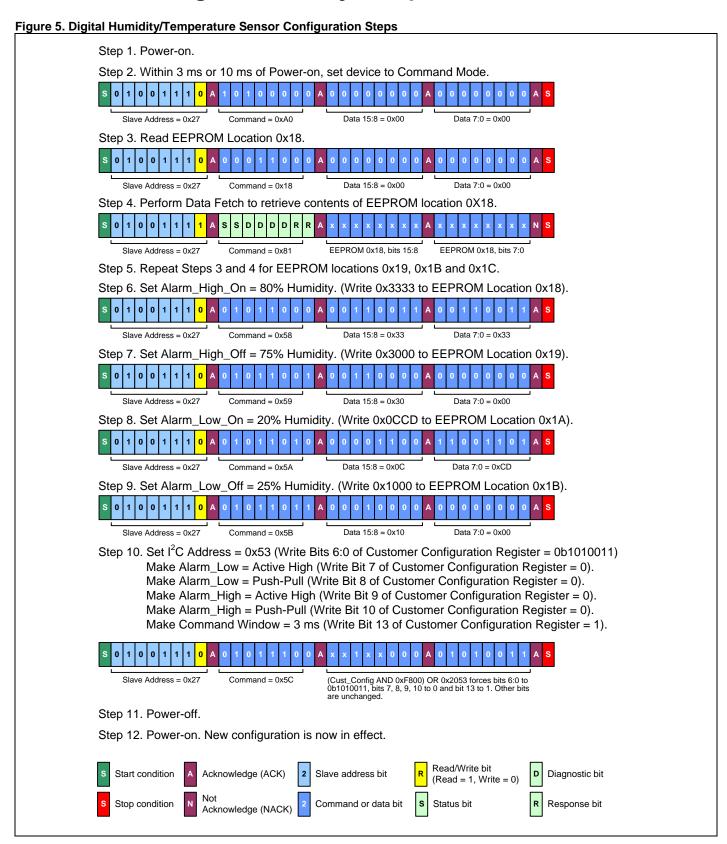
Table 6. Customer Configuration Register

Bit	Name	Description		
6:0	Device ID	I ² C slave address		
8:7	Alarm_Low_Cfg	configures the Alarm_Low output pin		
		Bit	Description	
		7	alarm polarity: 0 = Active_High 1 = Active_Low	
		8	output configuration: 0 = Full_Push-Pull 1 = Open_Drain	
10:9 Alarm_High_Cfg		Configures the Alarm_High output pin		
		Bit	Description	
		9	alarm polarity: 0 = Active_High 1 = Active_Low	
		10	output configuration: 0 = Full_Push-Pull 1 = Open_Drain	
11	reserved	do not change; must be left at factory setting		
12	reserved	do not change; must be left at factory setting		
13	fast startup	sets the Command Window duration: 0 = 10 ms, 1 = 3 ms		
15:14	reserved	do not change; must be left at factory setting		

NOTICE

Read and store the original EEPROM contents before modifying them in case the sensor must be returned to its default condition.

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Internet: www.honeywell.com/sensing

Phone and Fax:

Asia Pacific +65 6355-2828

+65 6445-3033 Fax

Europe +44 (0) 1698 481481

+44 (0) 1698 481676 Fax

+1-305-805-8188 Latin America

+1-305-883-8257 Fax

USA/Canada +1-800-537-6945 +1-815-235-6847

+1-815-235-6545 Fax

Sensing and Control Honeywell 1985 Douglas Drive North Golden Valley, MN 55422 www.honeywell.com/sensing

