

SMART Position Sensors, Rotary Configuration

DESCRIPTION

Honeywell's SMART Position Sensors are some of the most durable, adaptable, and lightweight absolute position sensors available in the industry, enabling enhanced accuracy in motion control and improving operational efficiency and safety. The two-piece, fully non-contacting design facilitates ease of integration in the application, promoting performance even in the harshest environments.

Why is the SMART Position Sensor smart? Honeywell has utilized MR (Magnetoresistive) technology to provide enhanced accuracy and repeatable position sensing. The application of SMART sensing solutions provides critical system feedback, allowing for "smarter", more efficient function. This can translate to improved productivity, a safer work environment, and minimized cost of operations. The rotary configuration joins Honeywell's SMART Position Sensor family of proven linear and arc configurations.

The SMART Position Sensor, Rotary Configuration, is a non-contacting sensing solution for absolute position sensing with enhanced accuracy. It senses the position of a magnet relative to the sensor in a range of 0° to 360°. Honeywell uses a patented combination of an ASIC (Application Specific Integrated Circuit) and an array of MR sensors to reliably determine the position of a magnet collar attached to a rotating object. The SMART Position Sensor, Rotary Configuration, fits on a 25,4 mm [1 in] shaft. A mounting tool fixture (purchased separately) provides repeatable installation.

FEATURES

- Non-contact design minimizes mechanical failure mechanisms, can reduce wear, which promotes reliability and durability, and minimizes downtime
- Combined patented MR sensor and ASIC technology provides absolute position sensing:
 - Helps OEMs minimize warranty costs because they don't have to replace worn or broken component parts
 - Helps end-users minimize downtime due to fewer calibration requirements
- No internal moving parts: Automotive-grade potting makes the sensor more resistant to vibration, shock, and extreme temperatures, improving reliability
- Repeatable output: Occurs within a 3,0 mm ±2,0 mm [0.118 in ±0.079 in] air gap between the sensor and magnet collar, expanding application opportunities
- Enhanced accuracy: Measures values down to 0.01°; better sensor accuracy can provide better system accuracy in the application
- IP67 and IP69K sealing: Allows for use in harsh environments such as dust, immersion up to 1 m [39.37 in] of water for 30 minutes and high pressure water sprays
- Enhanced shock and vibration resistance: Allows for use in a wide variety of tough applications
- Minimal signal error: Exists up to 2,50 mm [0.10 in] of radial error, simplifying design-in
- RoHS-compliant: Materials meet Directive 2002/95/EC



APPLICATIONS

- Transportation
 - Steering angle
 - Articulation angle
 - Boom arm detection
- Industrial
 - Solar panels
 - Wind turbines

PORTFOLIO



The SMART Position Sensor, Rotary Configuration, is a non-contacting sensing solution for absolute position sensing with enhanced accuracy. To view the entire product portfolio, click [here](#).

SPS ROTARY SMART POSITION SENSOR

TABLE 1. 360° SPECIFICATIONS (SPS-R360D-NBMS0101)

	Min.	Typ.	Max.	Units
<i>Sensor Characteristics</i>				
Sensing range	–	360	–	Degree
Supply voltage	12	–	30	Vdc
Supply current	–	–	90	mA
Output type	Current Output			
Output at min. pos	–	4	–	mA
Output at max. pos	–	20	–	mA
Full scale span	–	16	–	mA
Offset (25°C [77°F]) ^{3,4,5,7}	-0.044	-0.011	0.022	%FS
TCO (>85°C [158°F]) ^{3,4,5,7}	–	0.0033	–	%FS/°C
Linearity (25°C [77°F]) ^{2,4,7}	-0.03	–	-0.03	%FS
Linearity (>85°C [158°F]) ^{2,4,7}	–	0.00011	–	%FS/°C
Sensitivity (25°C [77°F]) ^{6,7}	44.43	44.45	44.48	µA/Degree
TCS (>85°C [158°F]) ^{6,7}	–	0.00011	–	%FS/°C
Accuracy ⁴	-0.069	–	0.069	%FS
Sensitivity	38.4	40	41.6	mV/Degree
Linearity	± 0.4%			Full scale output
Resolution	0.01			Degree
Reverse polarity	-12	–	-30	V
Startup time	130			mS
<i>Connector</i>				
Termination	M12 connector, male 5-pin			
<i>Operating Environment</i>				
Operating temperature	-40°C to 85°C [-40°F to 185°F]			
Storage temperature	-40°C to 150°C [-40°F to 302°F]			
Air gap	3,0 mm ± 2,0 mm [0.118 in ±0.079 in]			
Ingress protection	IP67, IP69K			
Mechanical shock	50 G half sine wave with 11 ms duration			
Vibration	20 G from 10 Hz to 2000 Hz			
<i>Certification</i>				
Certification/approval	CE, UKCA			
<i>Mounting</i>				
Housing	Aluminium with Powder coating			
Mounting screws	UNC 10-24 or M5			
Mounting torque	5 Nm to 7 Nm [44.25 in-lb to 61.95 in-lb]			
<i>Magnet Actuator</i>				
Magnet	Neodymium Iron Boron			
Field strength	3700			Gauss

¹ Specifications are based on a non-ferrous shaft.

² Linearity: Deviations from a best fit straight line through the output, expressed as a percentage of the full scale signal range (% of 16 mA).

³ Accuracy: Deviations from the ideal output line expressed as a percentage of the full scale signal range (% of 16 mA).

⁴ %FS: Error expressed as a percentage of the output span of the sensor (% of 16 mA).

⁵ Offset: Deviation from the ideal output at the minimum input condition, expressed as a percentage of the full scale signal range (% of 16 mA).

⁶ Sensitivity: The slope of the output signal vs magnet travel, expressed as µA of output per degree of travel.

⁷ TC: Temperature coefficient of a given parameter, as a percentage of the full scale signal range (% of 16 mA) per degree of temperature rise from 25°C [77°F].

Stationary ferrous material often creates an initial offset upon installation. If the stationary ferrous material never moves in relation to the sensor after the installation, and the environment remains ferrous-free, performance should be repeatable. Ensure the sensor is tested in the application.

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TABLE 2. % LINEARITY

		Radial Error (mm)									
		0	0,05	0,1	0,25	0,5	0,75	1	1,5	2	2,5
Air gap error (mm)	-2	0.005	0,001	0,007	0,027	0,066	0,113	0,166	0,294	0,450	0,635
	-1	0.002	0,003	0,008	0,025	0,060	0,101	0,150	0,269	0,417	0,593
	0	0.000	0,004	0,008	0,023	0,053	0,090	0,135	0,245	0,383	0,550
	1	0.002	0,005	0,009	0,021	0,047	0,079	0,119	0,220	0,350	0,508
	2	0.005	0,007	0,009	0,019	0,040	0,068	0,104	0,196	0,317	0,466
	3	0.007	0,008	0,010	0,017	0,033	0,057	0,088	0,172	0,284	0,424

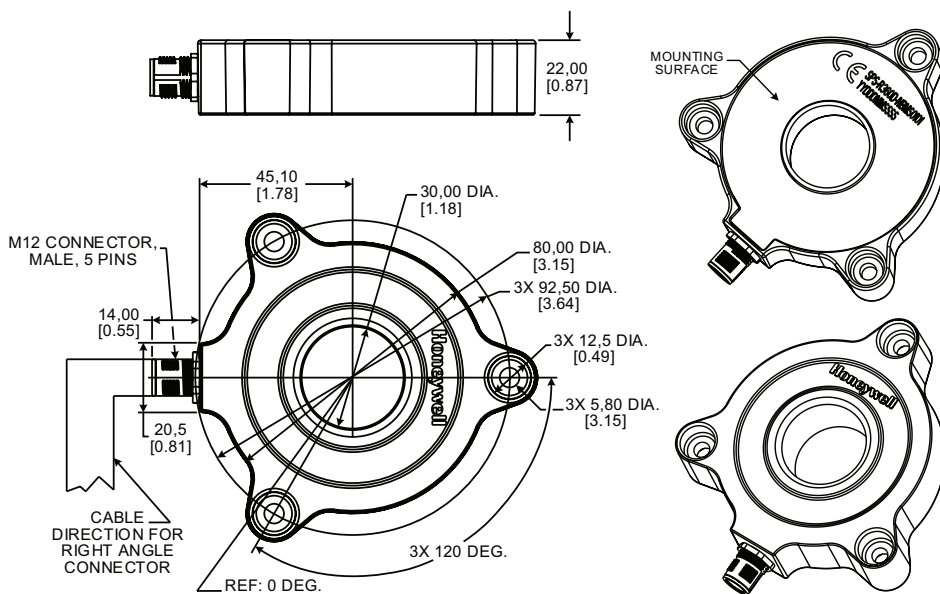
TABLE 3. % ACCURACY

		Radial Error (mm)									
		0	0,05	0,1	0,25	0,5	0,75	1	1,5	2	2,5
Air gap error (mm)	-2	0	0,006	0,012	0,033	0,076	0,129	0,191	0,263	0,538	0,770
	-1	0	0,005	0,011	0,029	0,069	0,118	0,176	0,245	0,509	0,733
	0	0	0,004	0,009	0,026	0,061	0,106	0,162	0,226	0,479	0,697
	1	0	0,004	0,008	0,022	0,054	0,095	0,147	0,208	0,450	0,660
	2	0	0,003	0,006	0,018	0,047	0,084	0,132	0,190	0,420	0,623
	3	0	0,002	0,005	0,015	0,039	0,073	0,117	0,171	0,391	0,586

NOTICE FERROUS MATERIAL

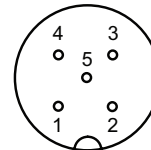
Stationary ferrous material often creates an initial offset upon installation. If the stationary ferrous material never moves in relation to the sensor after the installation, and the environment remains ferrous-free, performance should be repeatable. Ensure the sensor is tested in the application.

Figure 1. Sensor Dimensional Drawings (For reference only: mm [in].)



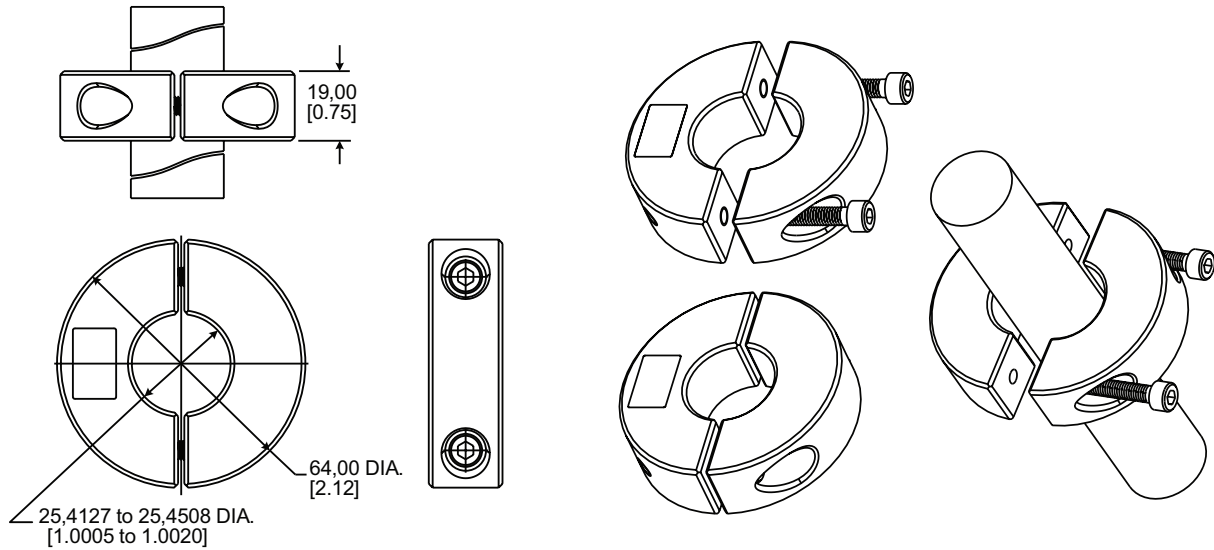
Pinout

- 1** = Supply voltage (+)
- 2** = Test pin, connect to ground (-)
- 3** = Ground (-)
- 4** = Output (O)
- 5** = Test pin, connect to ground (-)



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Figure 2. Magnet Collar Dimensional Drawings (For reference only: mm [in].)



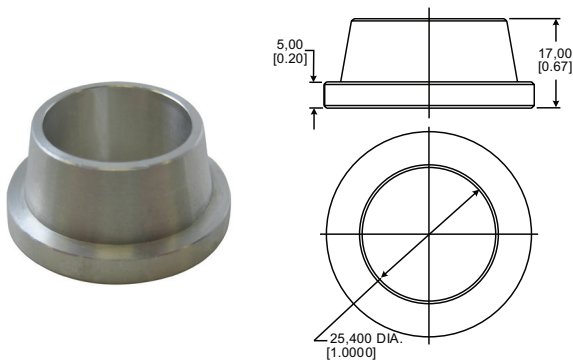
NOTICE

ASSEMBLY TOOL USE

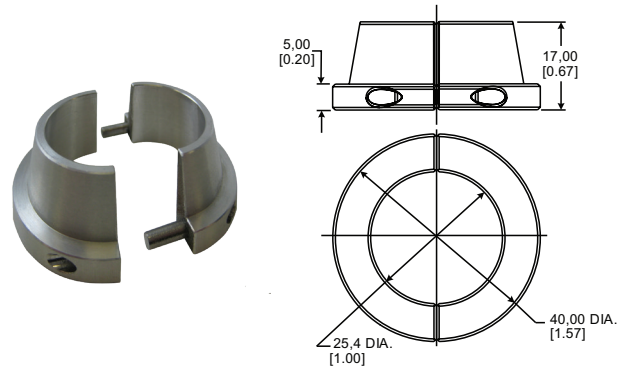
Honeywell recommends using an assembly tool to help align the magnetic axis of rotation to the inside diameter of the sensor.

Figure 3. Assembly Tools

One Piece (SPS-AUX-AS100-1)

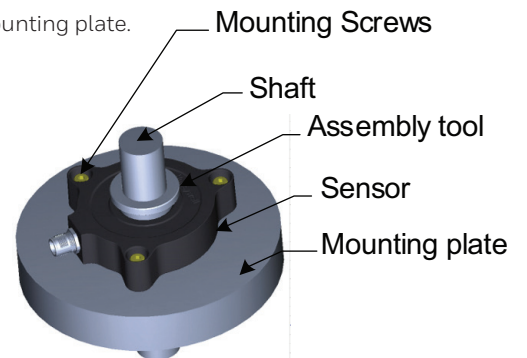


Two Piece (SPS-AUX-AS100-2)



Assembly Tool Use

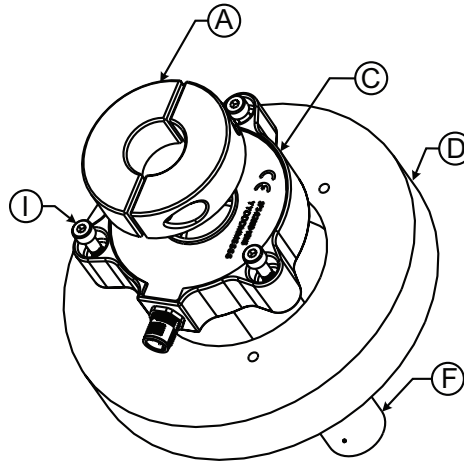
1. Place the sensor over the shaft with its epoxy side facing the mating surface of the mounting plate.
2. Loosely assemble the mounting screws in the sensor.
3. Install the assembly tool on the shaft.
4. Push the assembly tool into the rotary sensor to center on the shaft.
5. Tighten the sensor mounting screws while maintaining pressure on the assembly tool.
6. Remove the assembly tool.



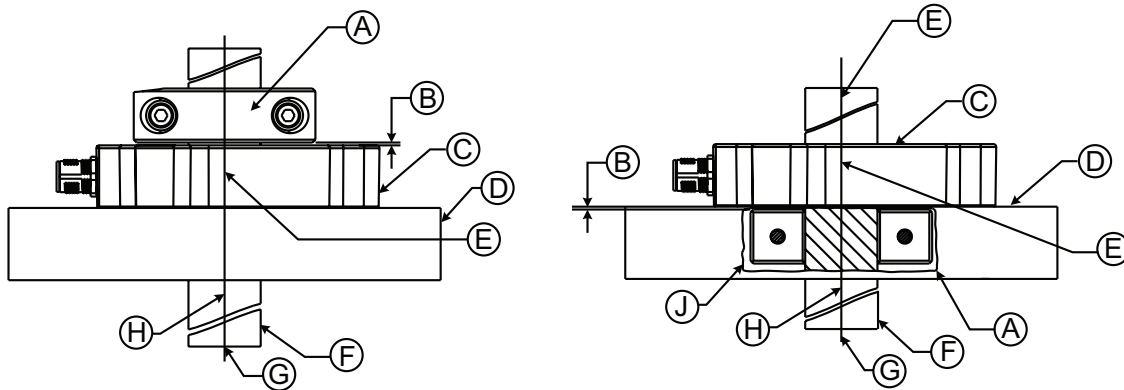
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Figure 4. Sensor Mounting Examples

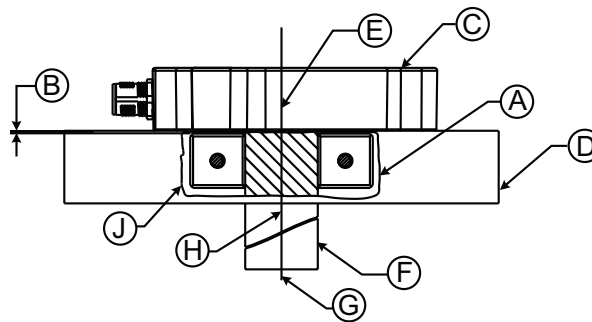
General



Through Shaft







Blind Shaft



- A** = Magnet collar (purchased separately)
- B** = Air gap (3,0 mm \pm 2,0 mm [0.118 in \pm 0.079 in] typ.)
- C** = Sensor
- D** = Mounting plate (customer supplied - provides surface to mount sensor)
- E** = Sensor axis
- F** = Shaft (customer supplied - provides shaft to attach magnet actuator)
- G** = Radial alignment (see Table 1)
- H** = Shaft axis
- I** = Mounting screws (customer supplied - M5 or UNC 10-24)
- J** = Recess

SPS ROTARY SMART POSITION SENSOR

TABLE 1. ORDER GUIDE

Catalog Listing	Description	
SPS-R360D-NBMS0101	SMART Position Sensor, rotary configuration, 360° sensing range, 4 mA to 20 mA output (magnet collar not included)	
SPS-MAG-002¹	Magnet collar for 25,4 mm [1 in] corresponding shaft diameter (sold separately)	
SPS-AUX-AS100-1¹	Assembly tool, one piece, 25,4 mm [1 in], aluminum (sold separately)	
SPS-AUX-AS100-2¹	Assembly tool, two piece, 25,4 mm [1 in], aluminum (sold separately)	

¹ Custom sizes are available if volume thresholds are met.

WARRANTY/REMEDY

Honeywell warrants goods of its manufacture as being free of defective materials and faulty workmanship during the applicable warranty period. Honeywell's standard product warranty applies unless agreed to otherwise by Honeywell in writing; please refer to your order acknowledgment or consult your local sales office for specific warranty details. If warranted goods are returned to Honeywell during the period of coverage, Honeywell will repair or replace, at its option, without charge those items that Honeywell, in its sole discretion, finds defective. The foregoing is buyer's sole remedy and is in lieu of all other warranties, expressed or implied, including those of merchantability and fitness for a particular purpose. In no event shall Honeywell be liable for consequential, special, or indirect damages.

While Honeywell may provide application assistance personally, through our literature and the Honeywell web site, it is buyer's sole responsibility to determine the suitability of the product in the application.

Specifications may change without notice. The information we supply is believed to be accurate and reliable as of this writing. However, Honeywell assumes no responsibility for its use.

FOR MORE INFORMATION

Honeywell Advanced Sensing Technologies services its customers through a worldwide network of sales offices and distributors. For application assistance, current specifications, pricing or the nearest Authorized Distributor, visit [our website](#) or call:

USA/Canada	+1 302 613 4491
Latin America	+1 305 805 8188
Europe	+44 1344 238258
Japan	+81 (0) 3-6730-7152
Singapore	+65 6355 2828
Greater China	+86 4006396841

Honeywell Advanced Sensing Technologies

830 East Arapaho Road
Richardson, TX 75081
sps.honeywell.com/ast

WARNING MISUSE OF DOCUMENTATION

- The information presented in this product sheet is for reference only. Do not use this document as a product installation guide.
- Complete installation, operation and maintenance information is provided in the instructions supplied with each product.

Failure to comply with these instructions could result in death or serious injury.